

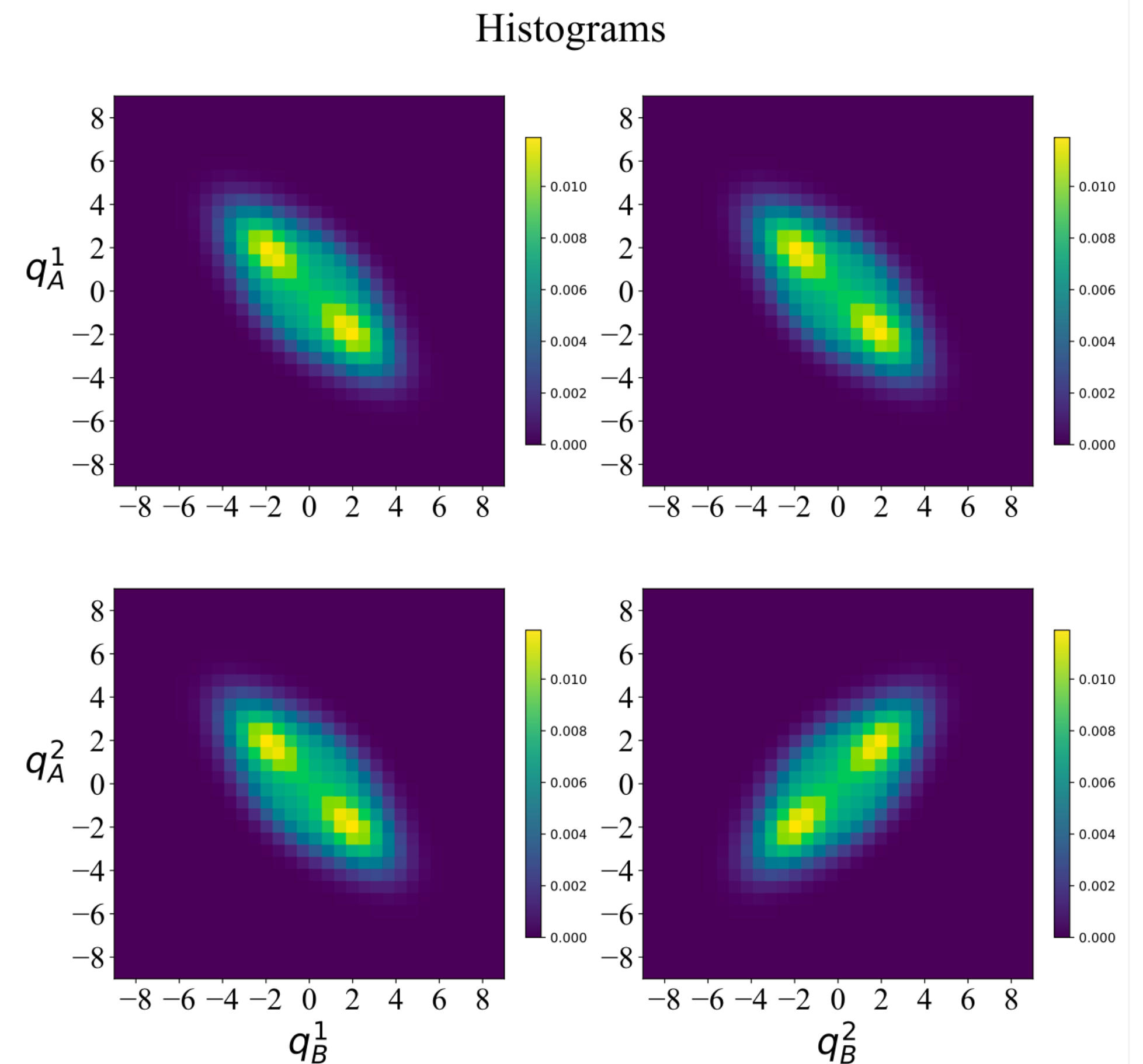
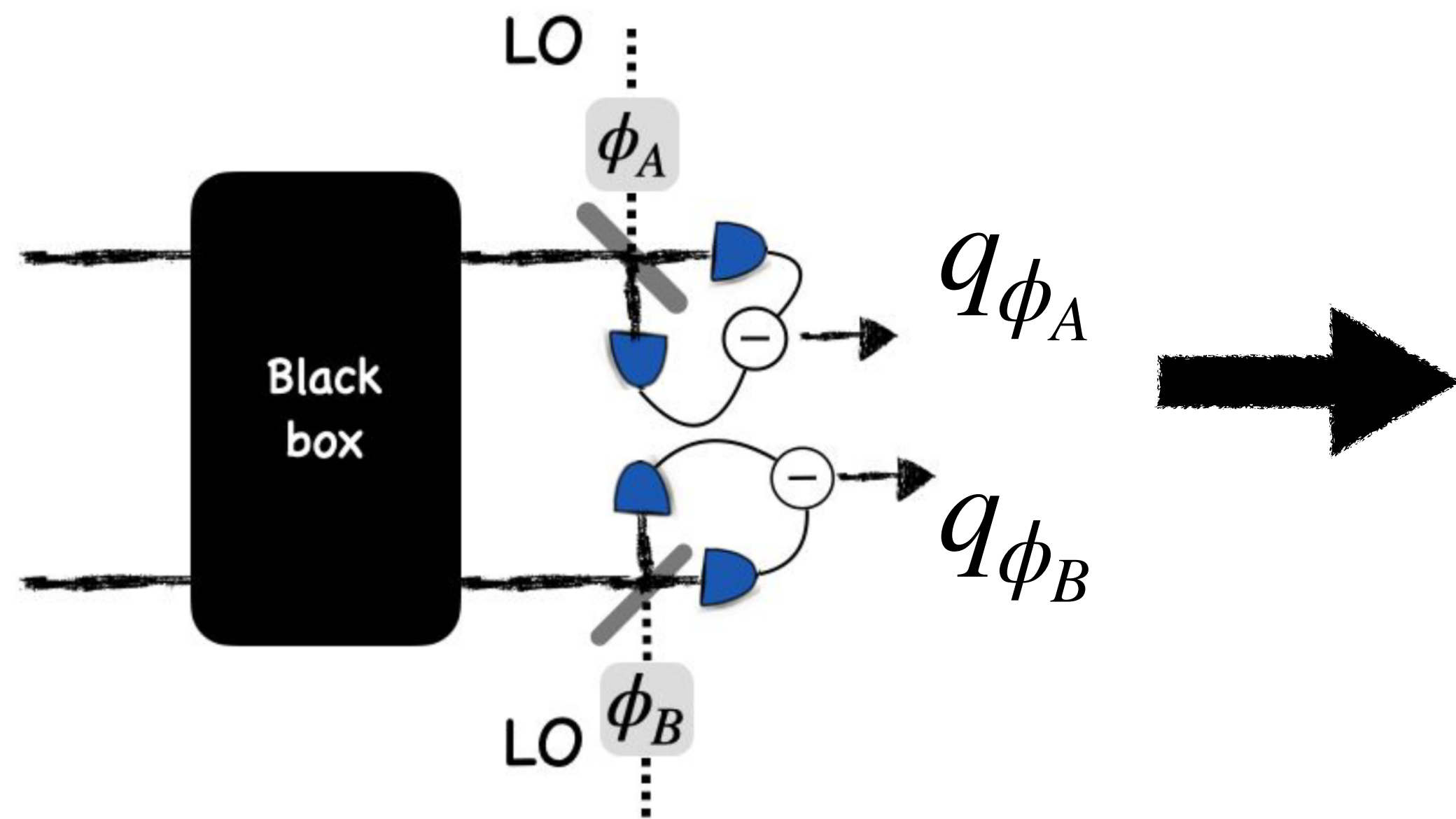
A general framework for (CV) Bell non-locality and contextuality

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Joint work with: P.E. Emeriau, Ulysse Chabaud, Uta I. Meyer, Enky Oudot, Gael Masse, Frederic Grosshams, Damien Markham, Robert Booth, Federico Centrone and Mattia Walschaers

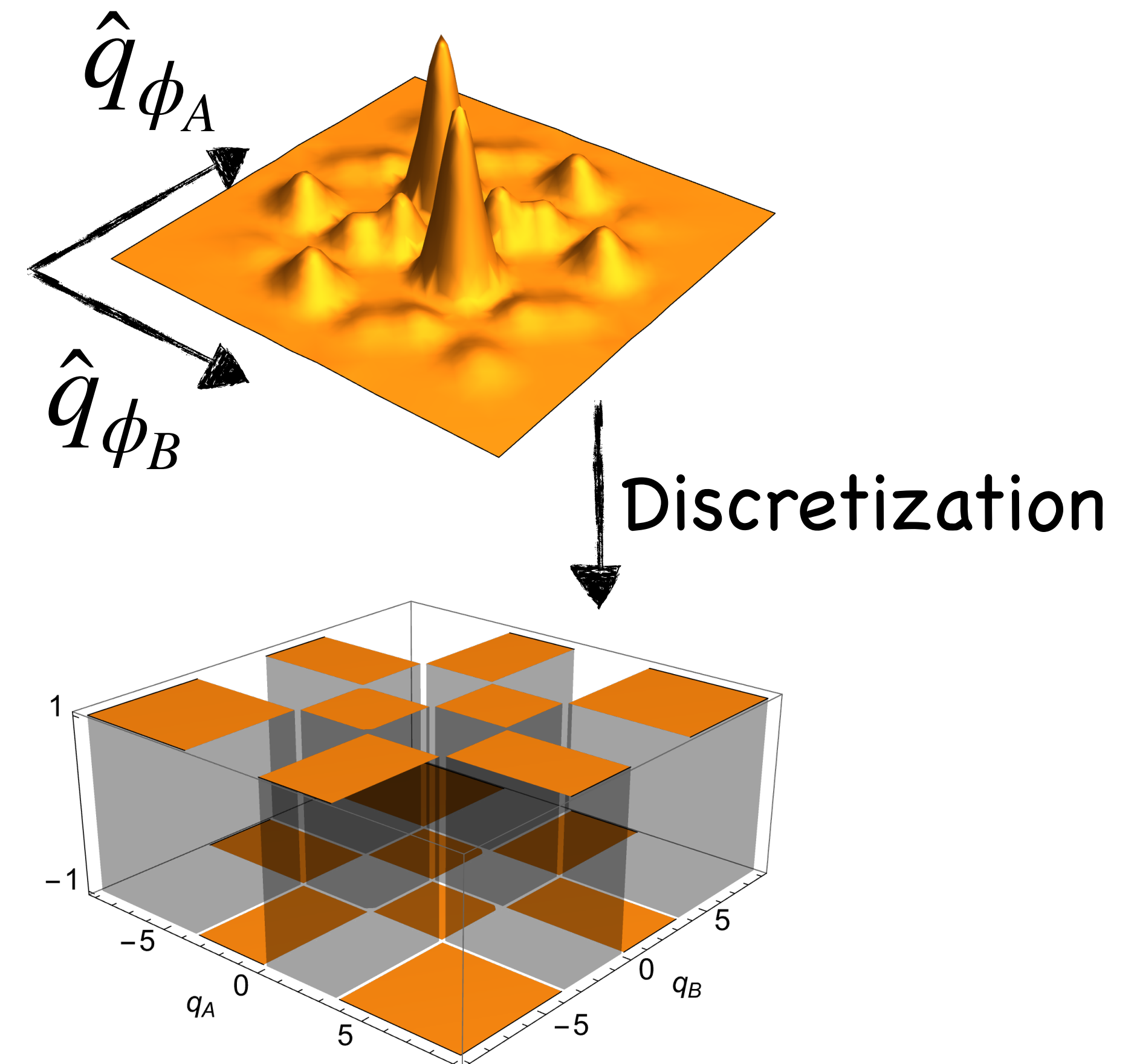
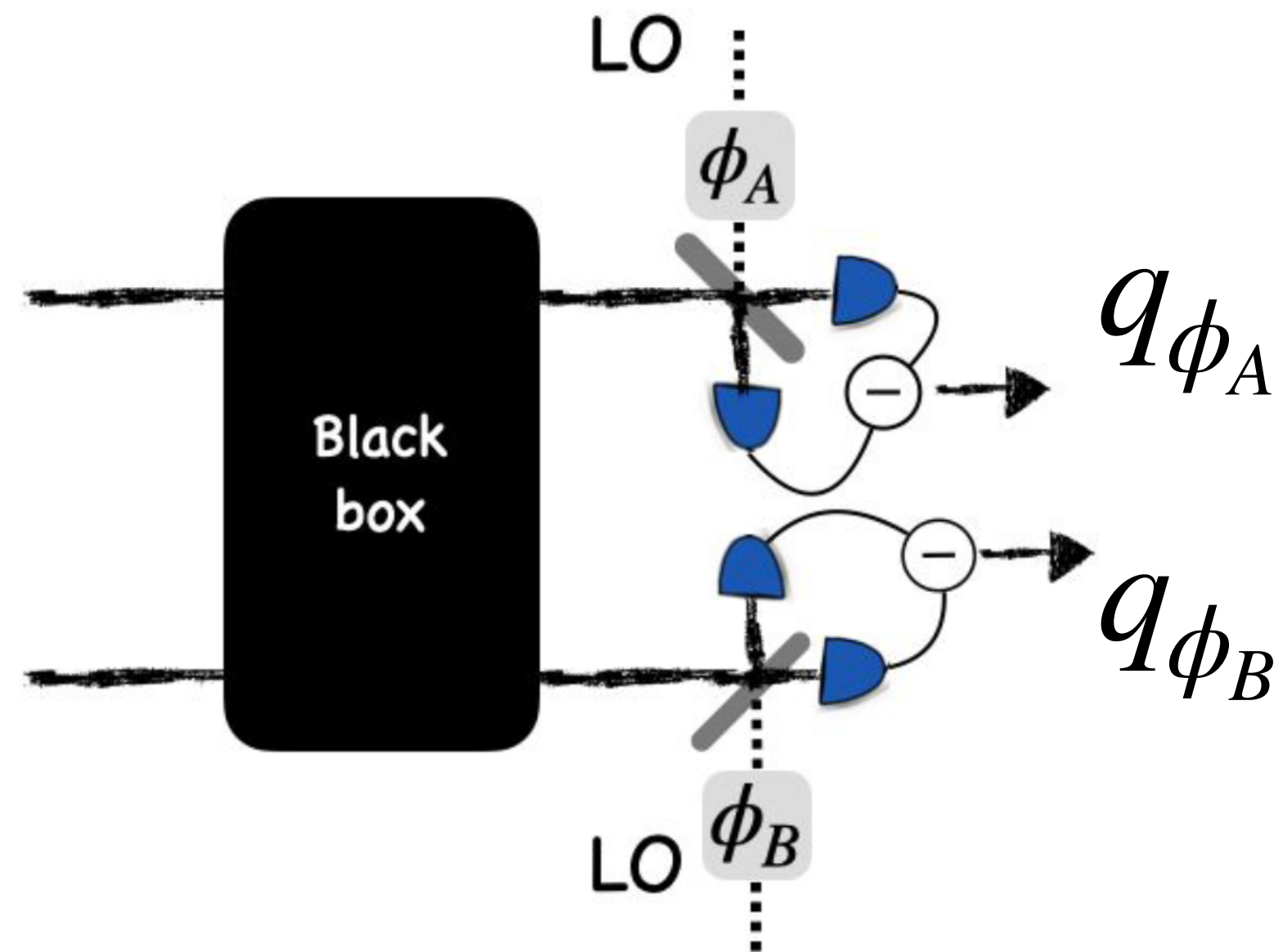
Objective:

Obtain some genuinely CV and practically relevant Bell inequality



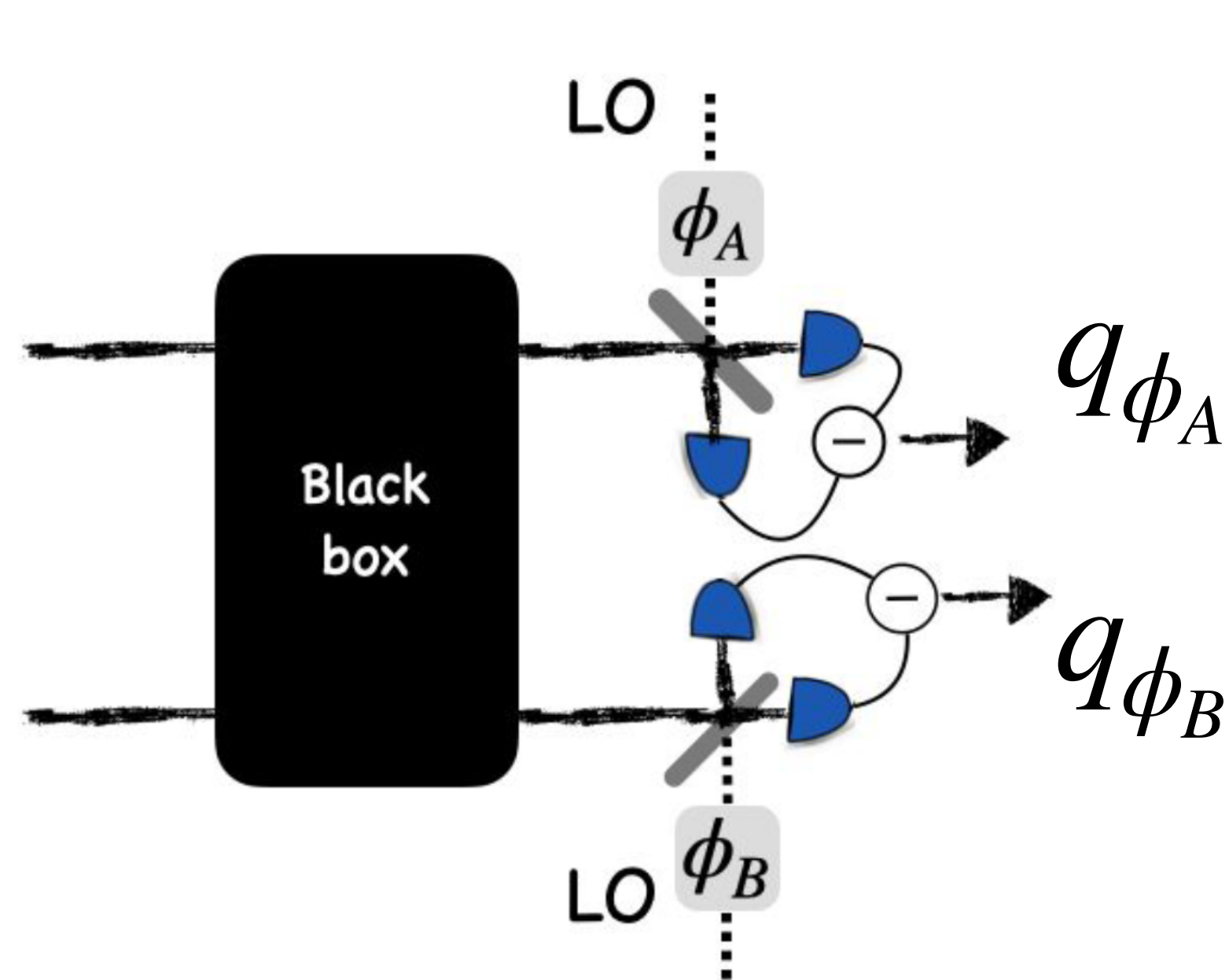
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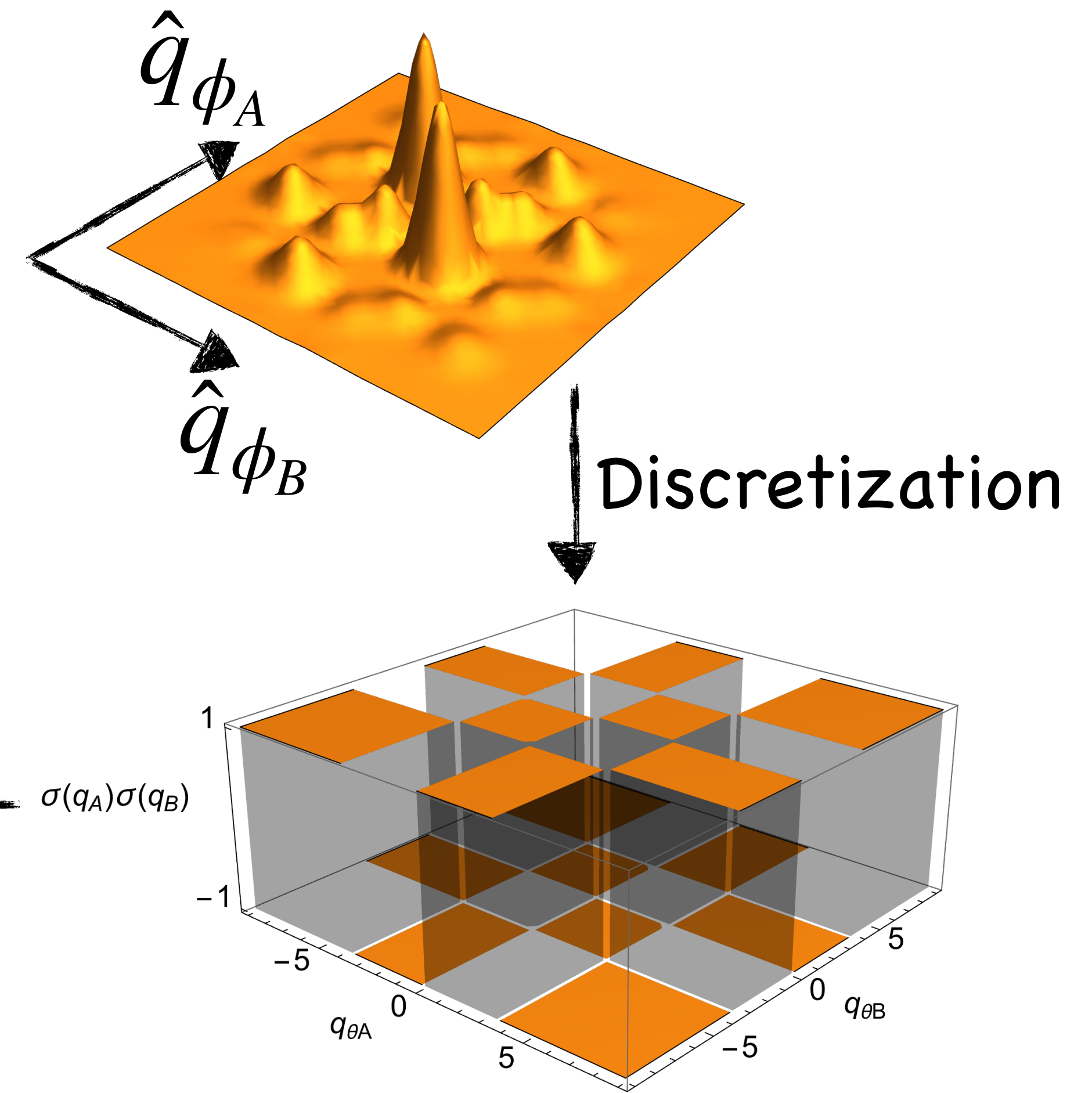
Objective:

Obtain some genuinely CV and practically relevant Bell inequality



Apply CHSH inequality

$$\langle \sigma_{\phi_A^{(1)}} \sigma_{\phi_B^{(1)}} \rangle + \langle \sigma_{\phi_A^{(1)}} \sigma_{\phi_B^{(2)}} \rangle + \langle \sigma_{\phi_A^{(2)}} \sigma_{\phi_B^{(1)}} \rangle - \langle \sigma_{\phi_A^{(2)}} \sigma_{\phi_B^{(2)}} \rangle \leq 2$$



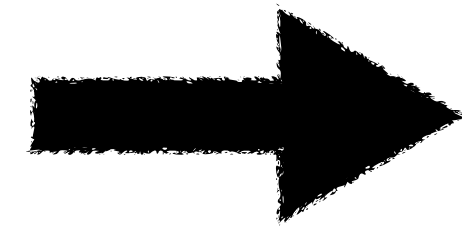
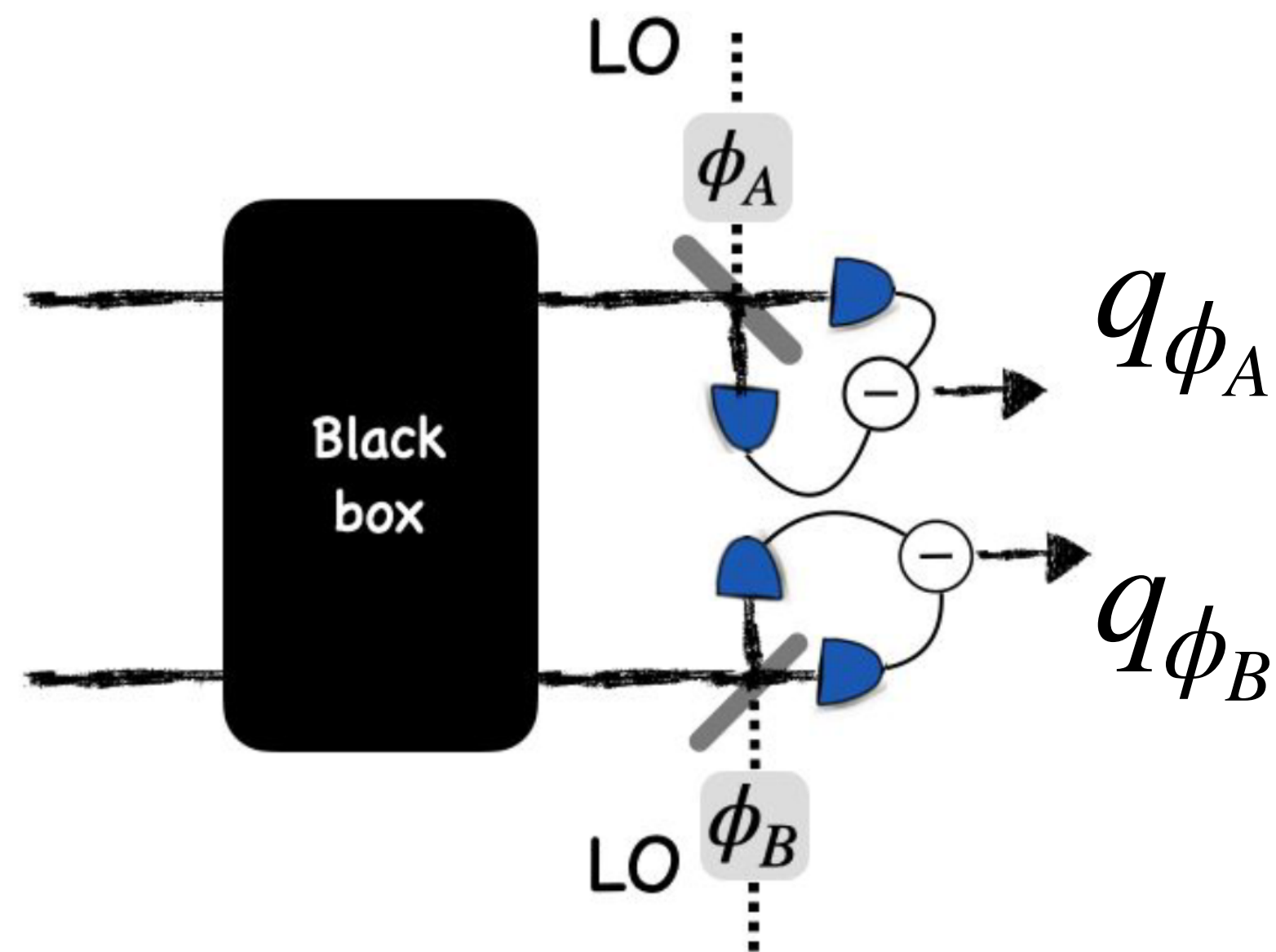
Theorem: For this kind of measurement scenario

Bell non-locality
(existence of a LHVM)

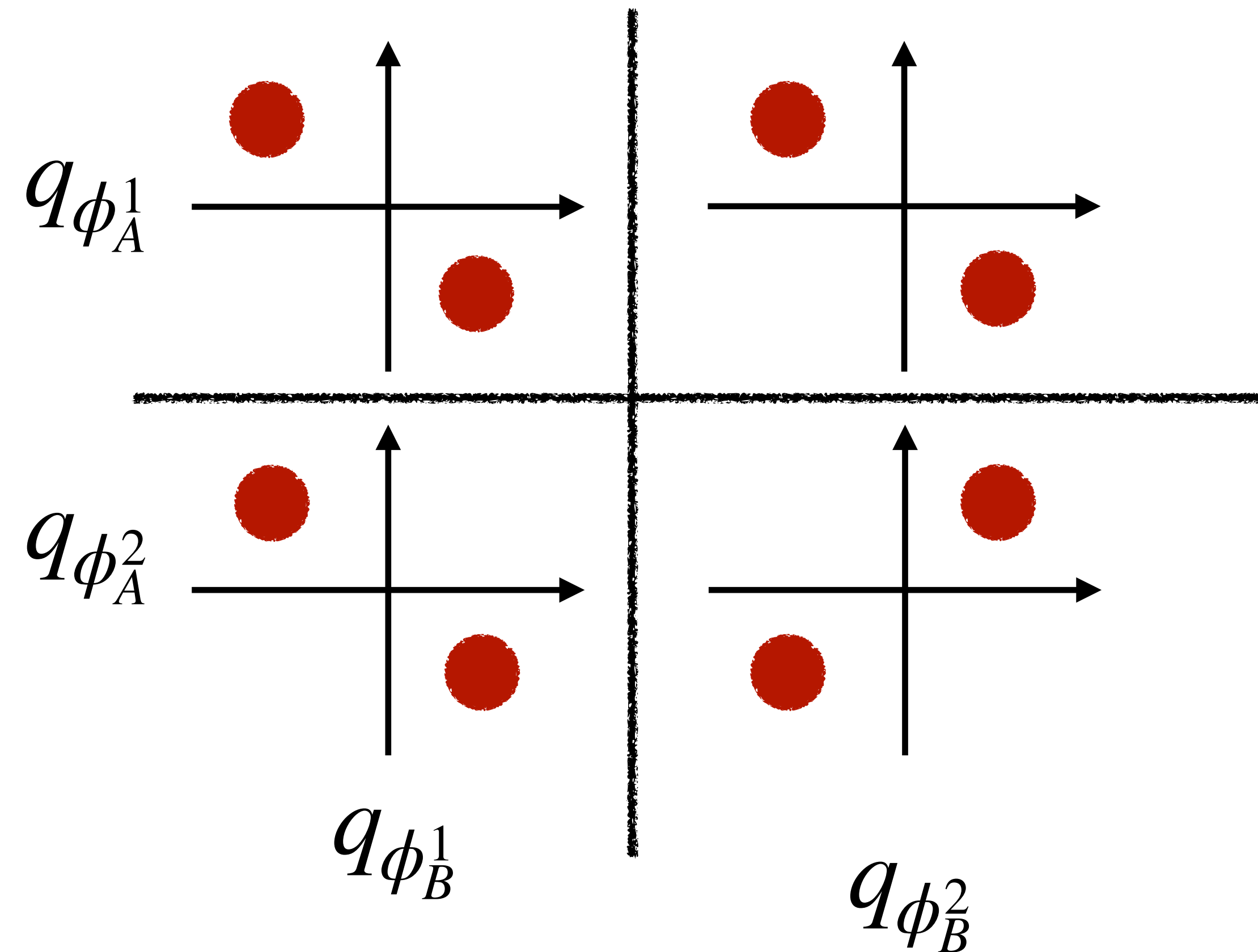


Contextuality

Measurement scenario

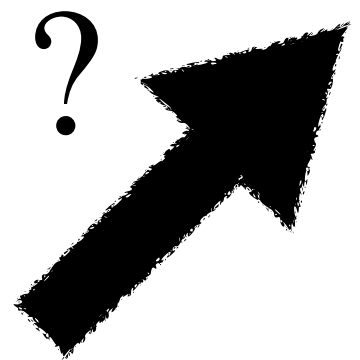
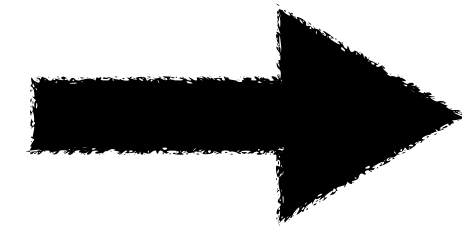
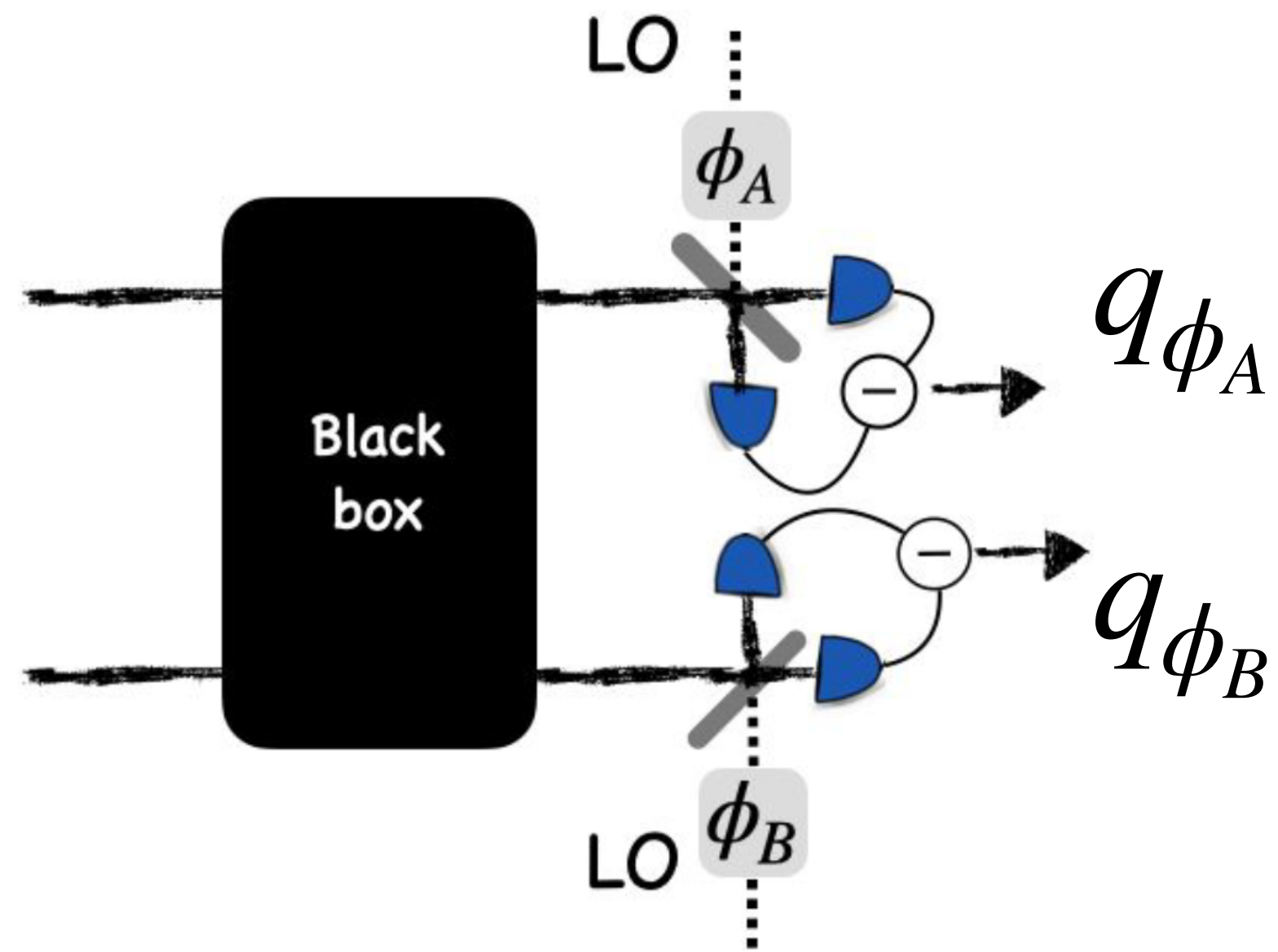


Empirical model

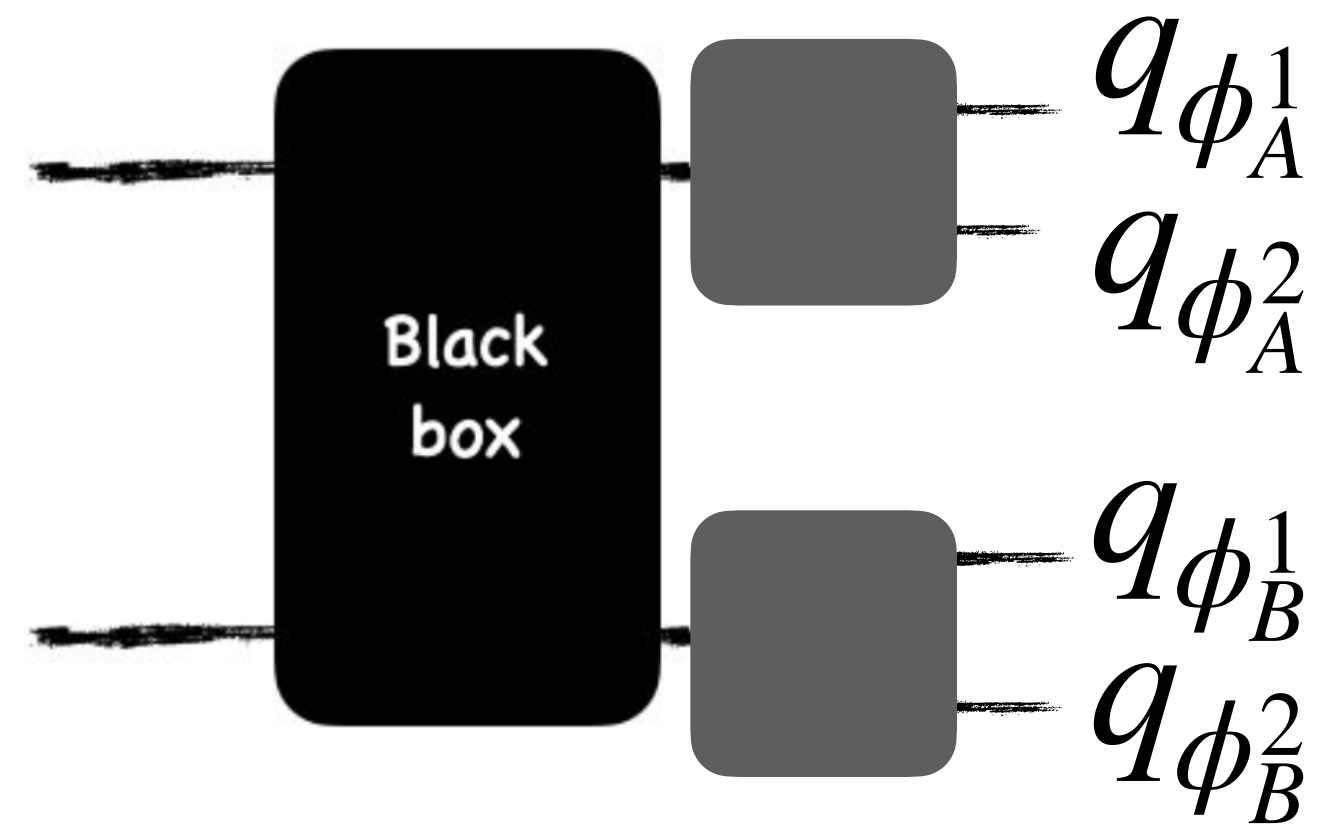
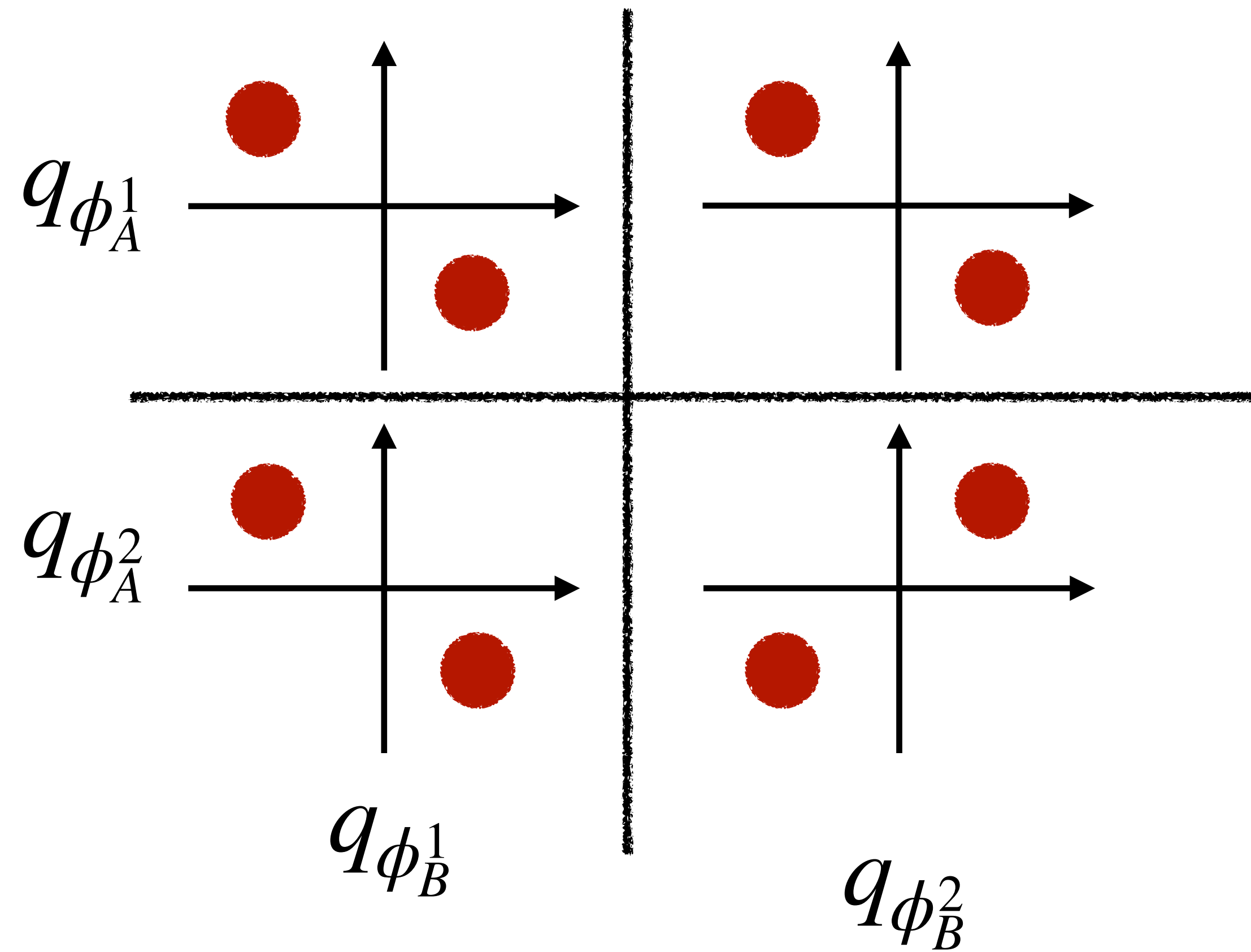


Non contextual if there is a global probability distribution that explains all the different contexts.

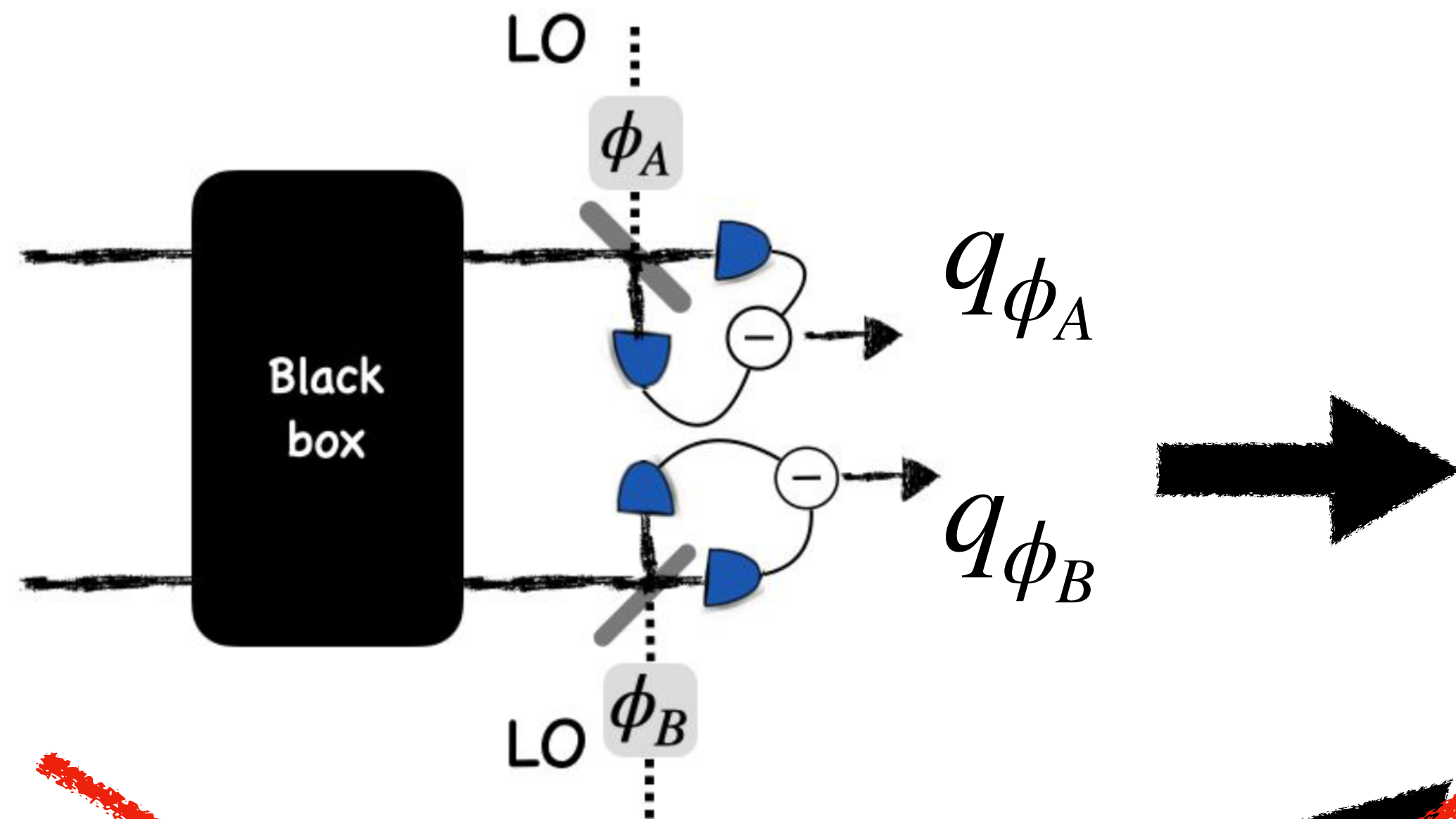
Measurement scenario



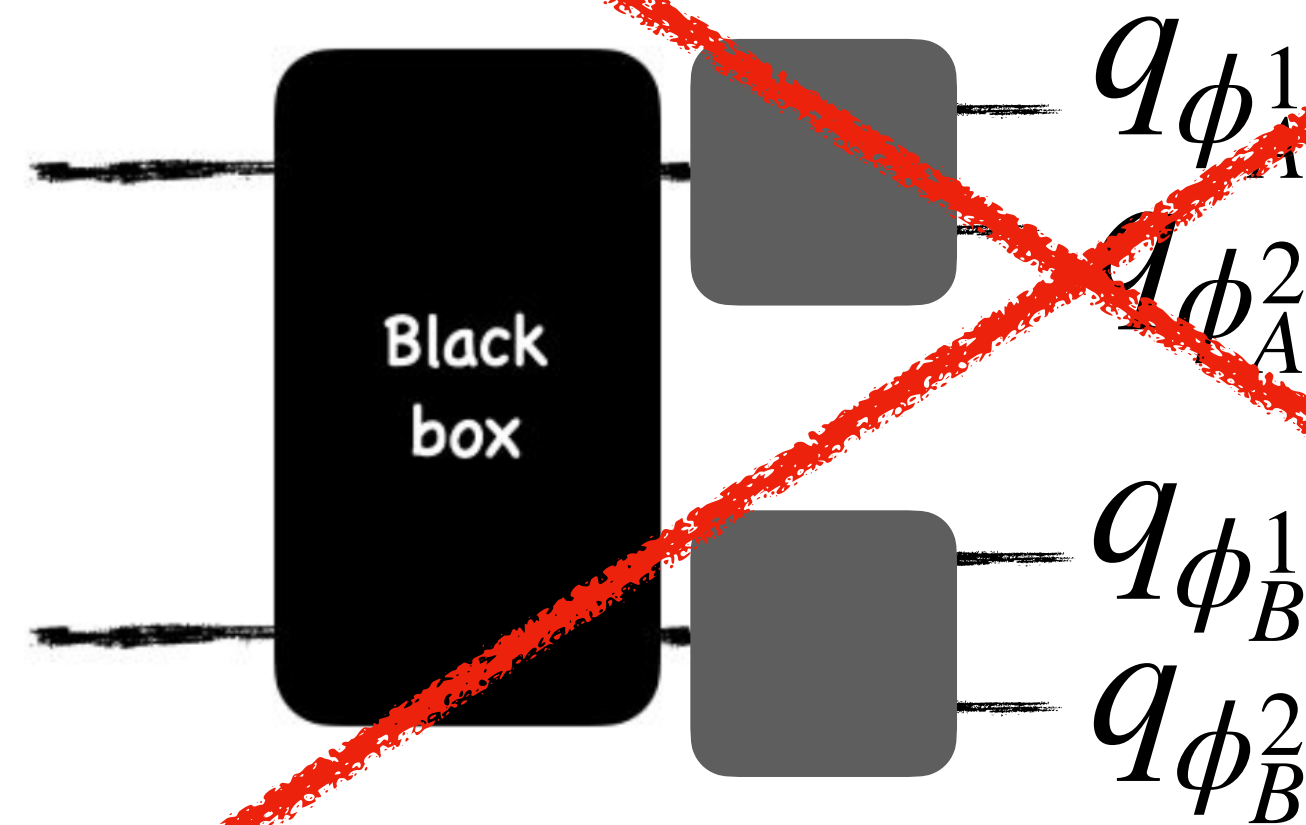
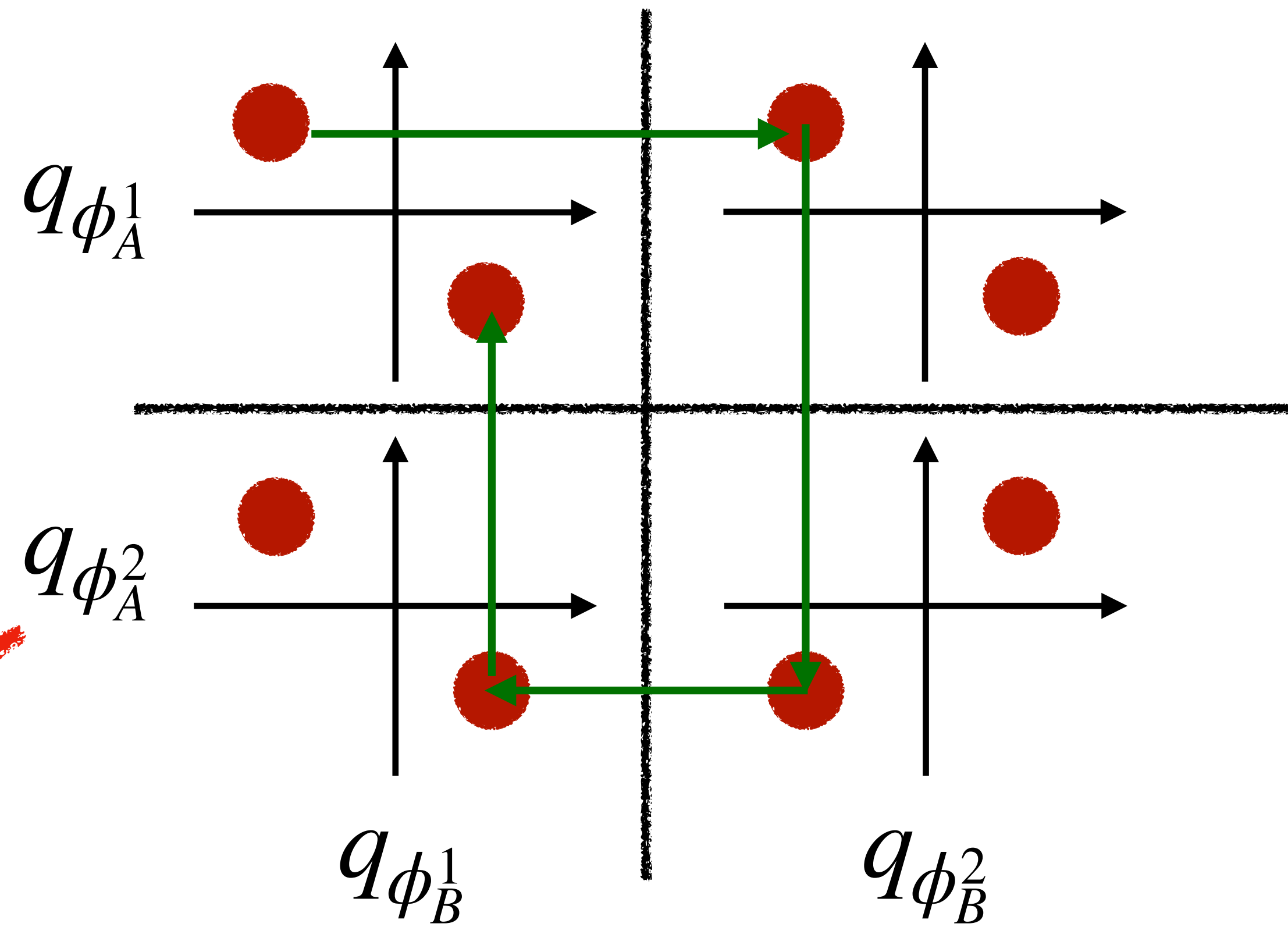
Empirical model



Measurement scenario

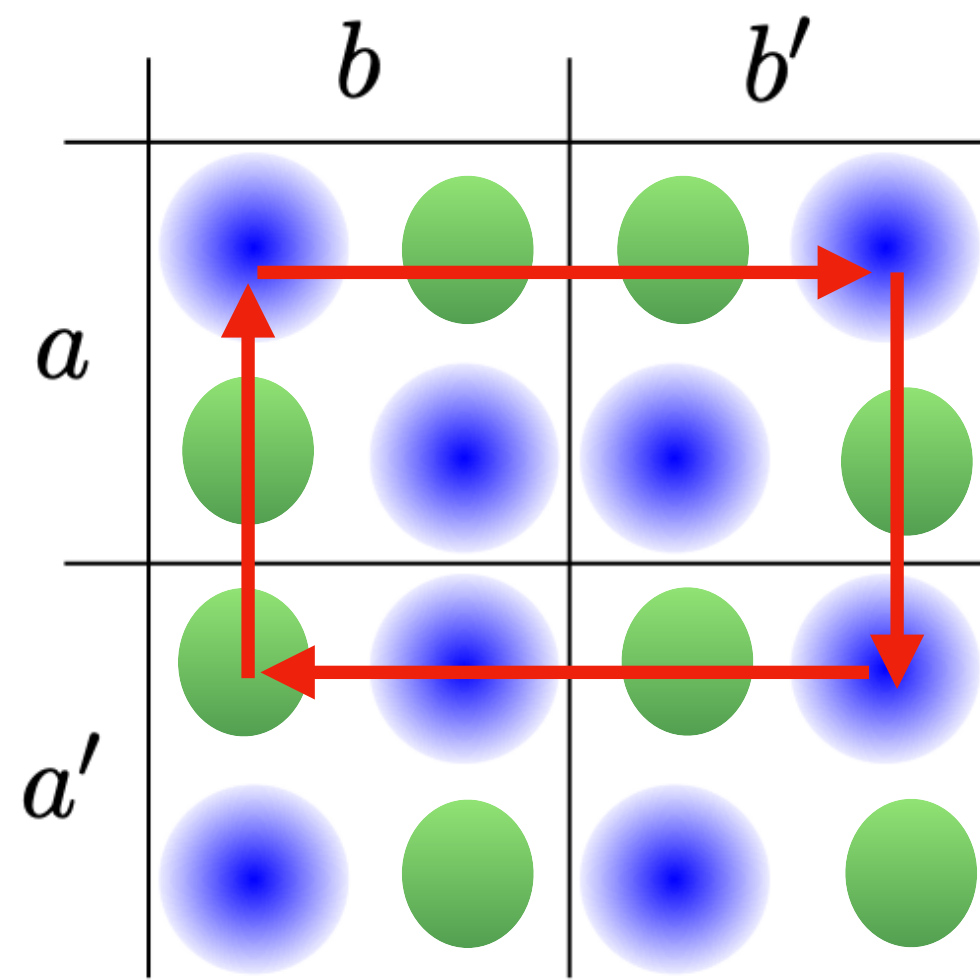


Empirical model



Quantifying contextuality

Intuition: what fraction of our measurement results are explained by a global probability distribution.

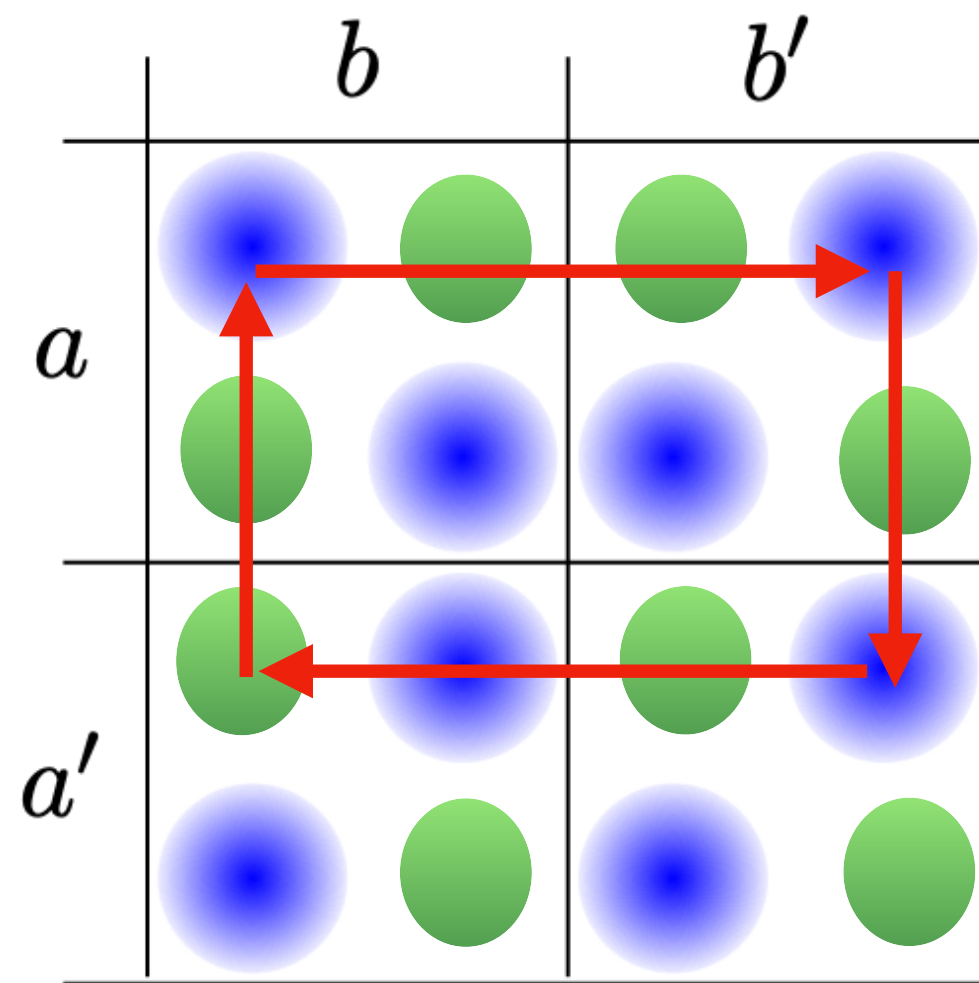


Intermediate behaviors are possible

non Contextual fraction > 0

Quantifying contextuality

Intuition: what fraction of our measurement results are explained by a global probability distribution.



Given empirical behavior its non contextual fraction is given by

$$\sup_{\mu \geq 0} \left(\int_{O_X} d\vec{x} \mu(a, a', b, b') \quad | \quad \forall C \in M : \mu_C(x_C^A, x_C^B) \leq e_C(x_C^A, x_C^B) \right)$$

Infinite Linear program:

Primal

$$\left\{ \begin{array}{l} \text{Find } \mu \in \mathbb{M}_{\pm}(\mathbf{O}_X) \\ \text{maximising } \mu(\mathbf{O}_X) \\ \text{subject to:} \\ \quad \forall C \in \mathcal{M}, \mu|_C \leq e_C \\ \quad \mu \geq 0 . \end{array} \right.$$



Dual

$$\left\{ \begin{array}{l} \text{Find } (f_C)_{C \in \mathcal{M}} \in \prod_{C \in \mathcal{M}} C(\mathbf{O}_C) \\ \text{minimising } \sum_{C \in \mathcal{M}} \int_{\mathbf{O}_C} f_C \, d e_C \\ \text{subject to:} \\ \quad \sum_{C \in \mathcal{M}} f_C \circ \rho_C^X \geq \mathbf{1}_{\mathbf{O}_X} \\ \quad \forall C \in \mathcal{M}, f_C \geq \mathbf{0}_{\mathbf{O}_C} . \end{array} \right.$$

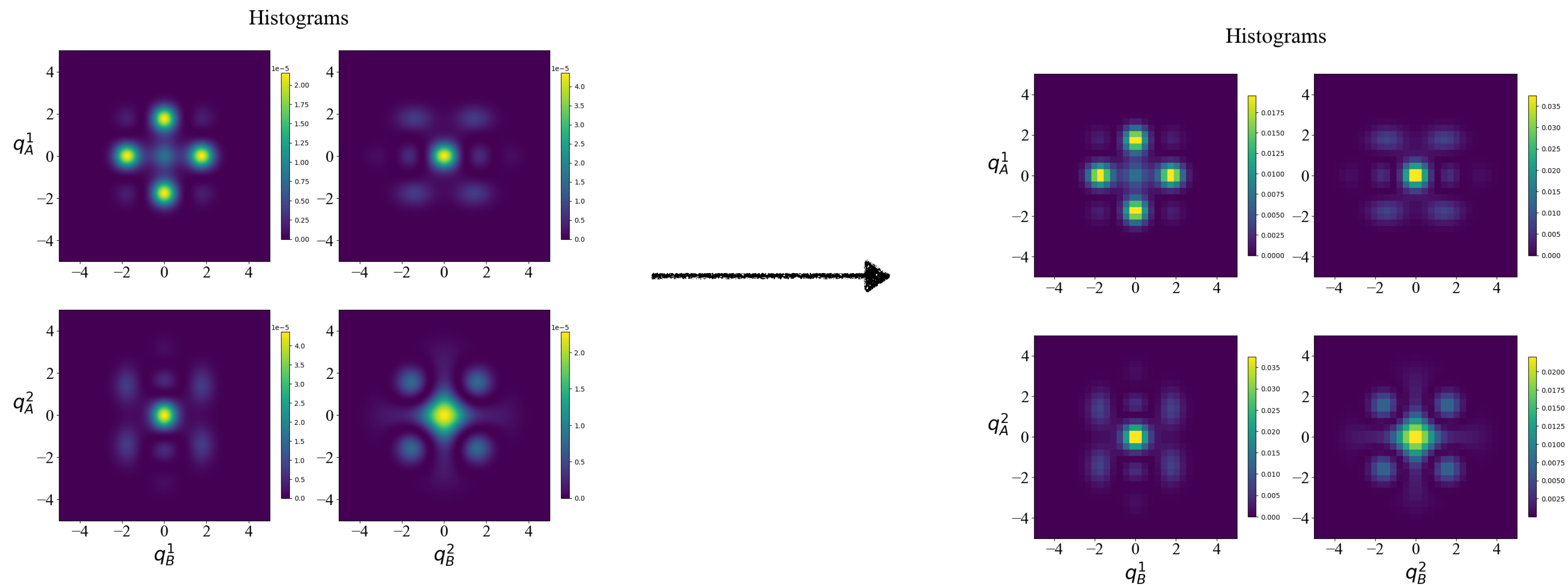
Relaxation of the infinite linear program

1- Moment based SDP hierarchy

Relaxation of the infinite linear program

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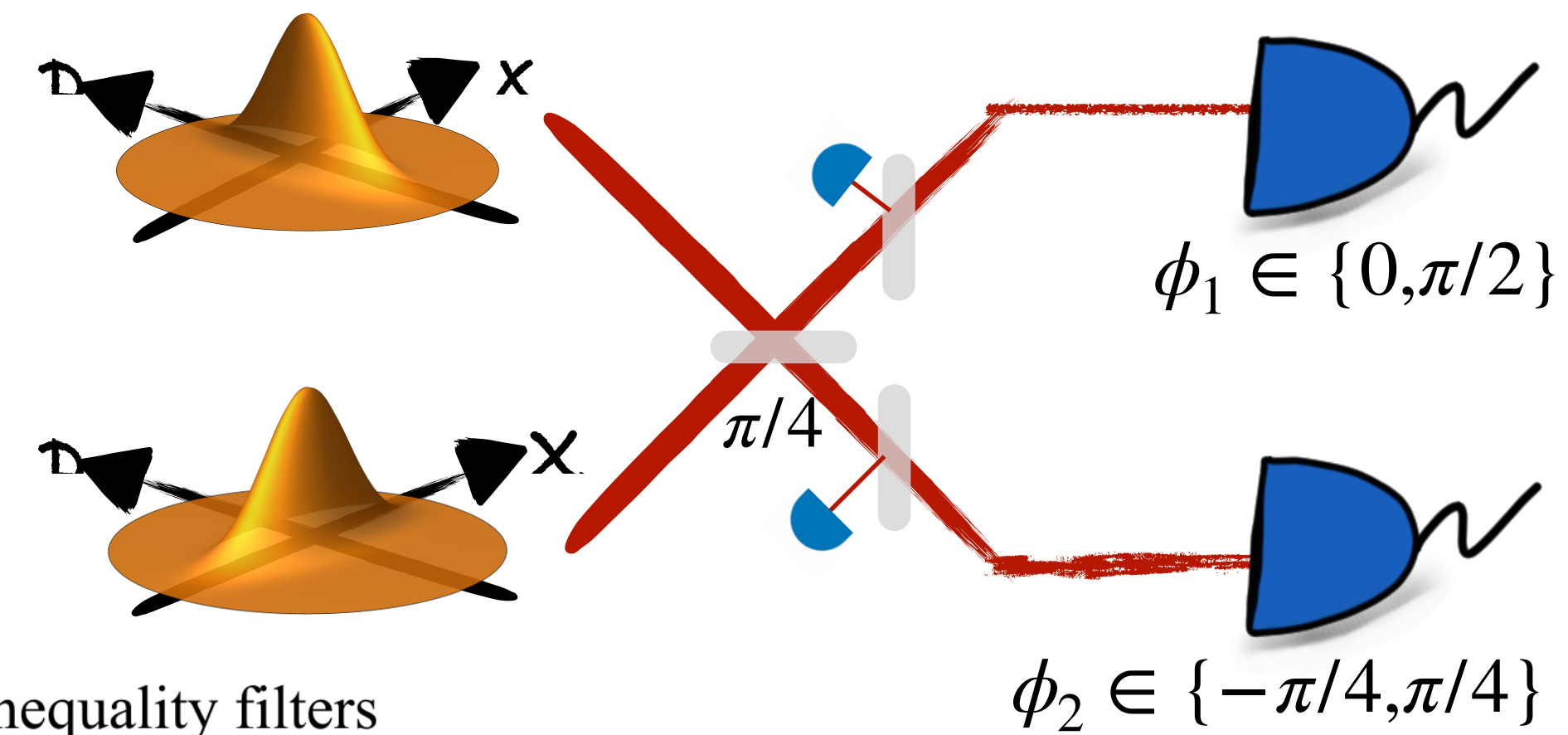
2- Finite Linear programs based on binning of the histograms



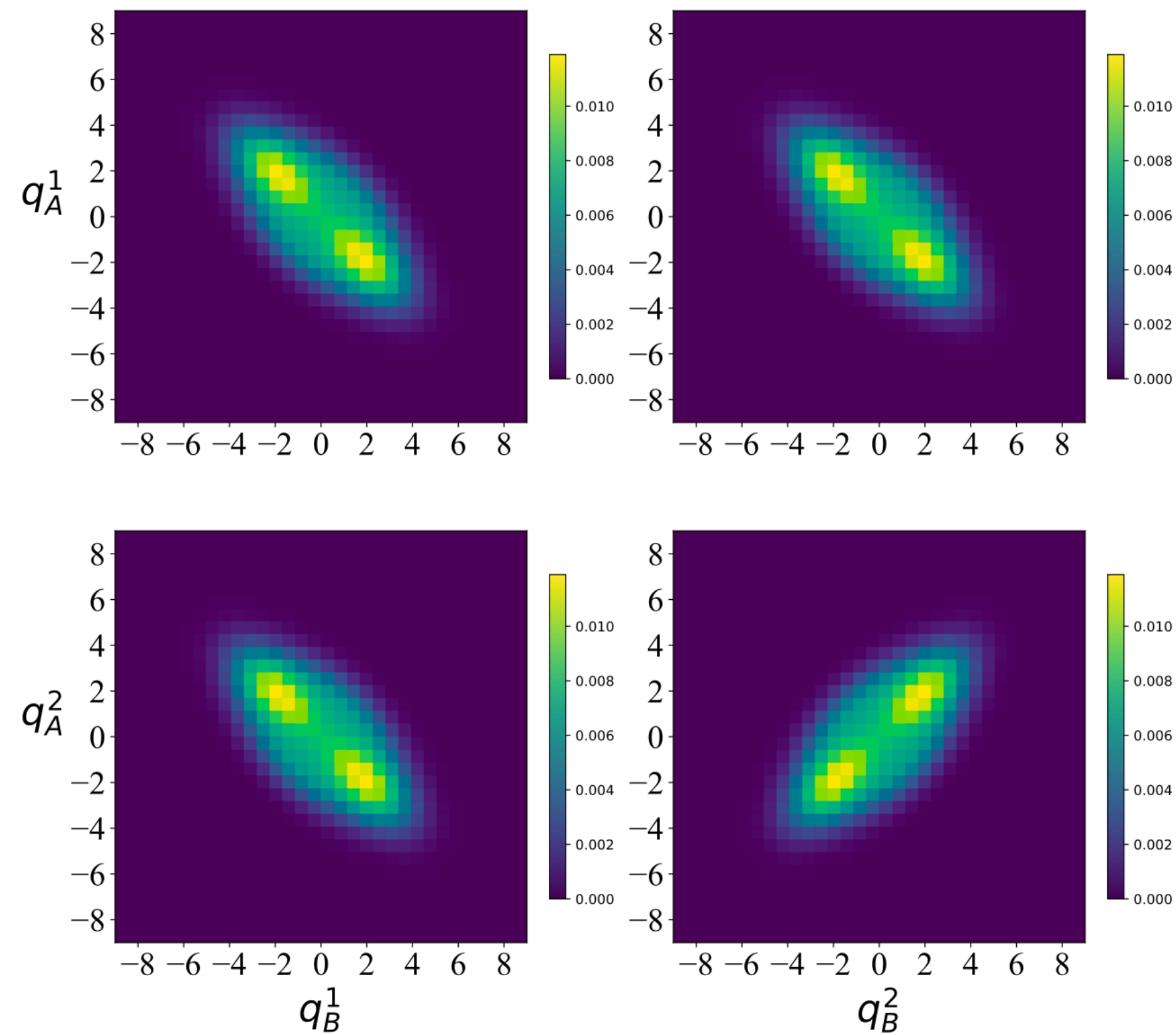
Two photon subtracted state

$$r_1 = -r_2 = 0.68(5.9dB)$$

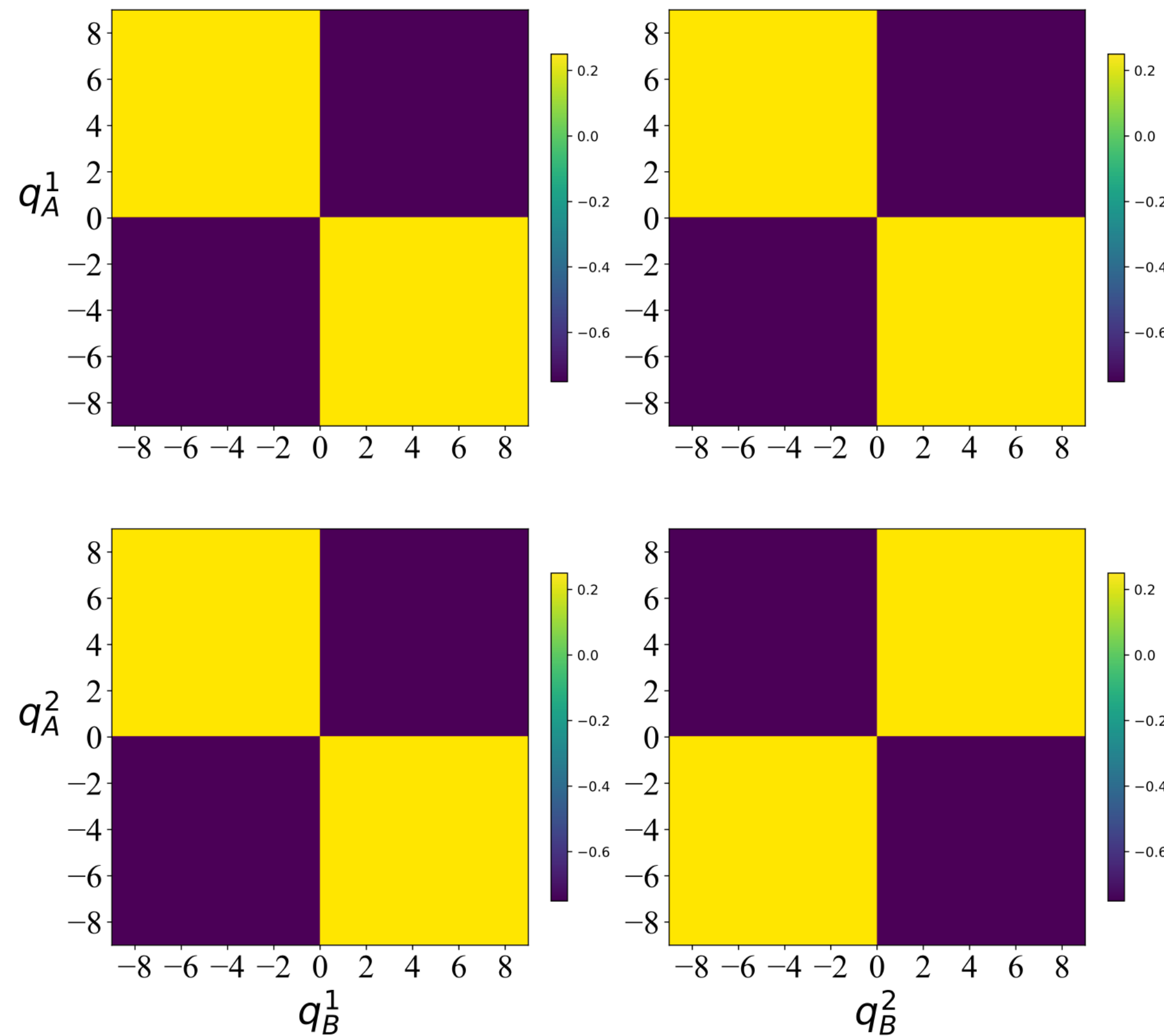
$$CF = 2.37\%$$



Histograms



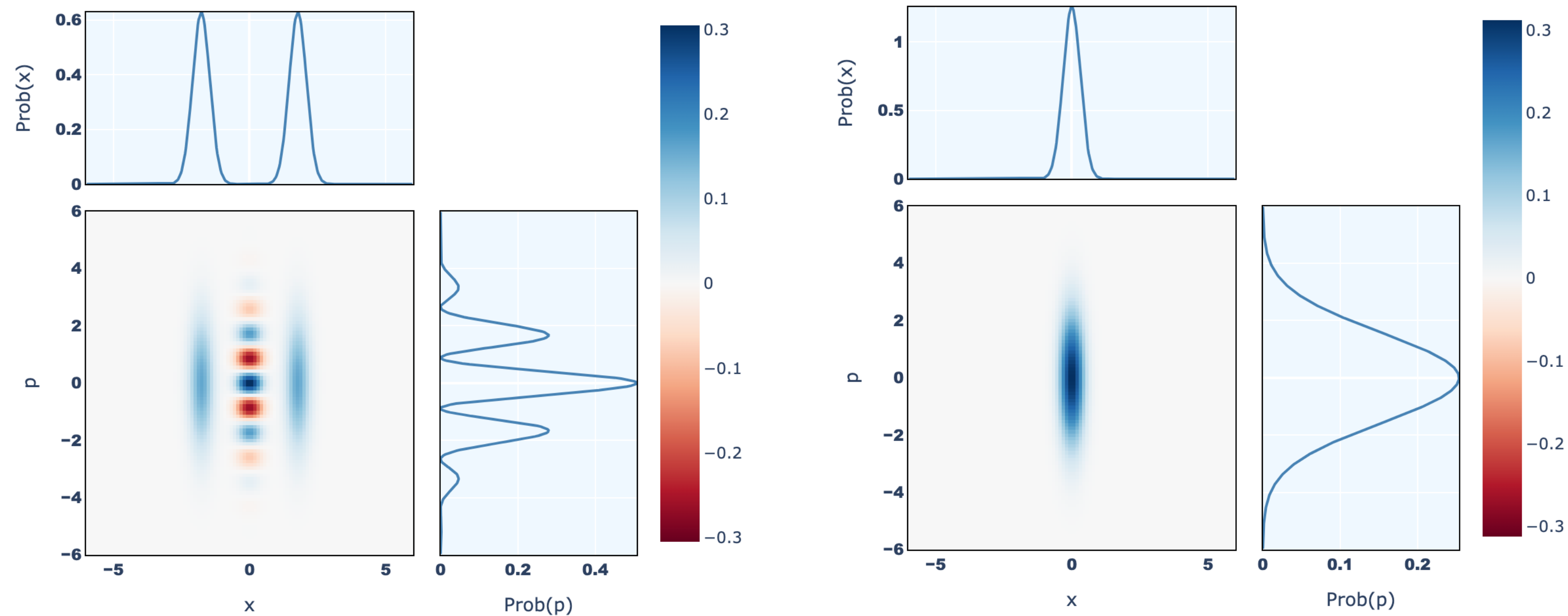
Bell inequality filters



«GKP» entangled state
$$|\psi\rangle = \frac{\left(|11\rangle - |00\rangle - (1 + \sqrt{2})(|01\rangle + |10\rangle) \right)}{2\sqrt{2 + \sqrt{2}}}$$

$$|0\rangle = \frac{|\alpha, r\rangle + |-\alpha, r\rangle}{\sqrt{2}}$$

$$|1\rangle = \hat{S}(r)|0\rangle$$

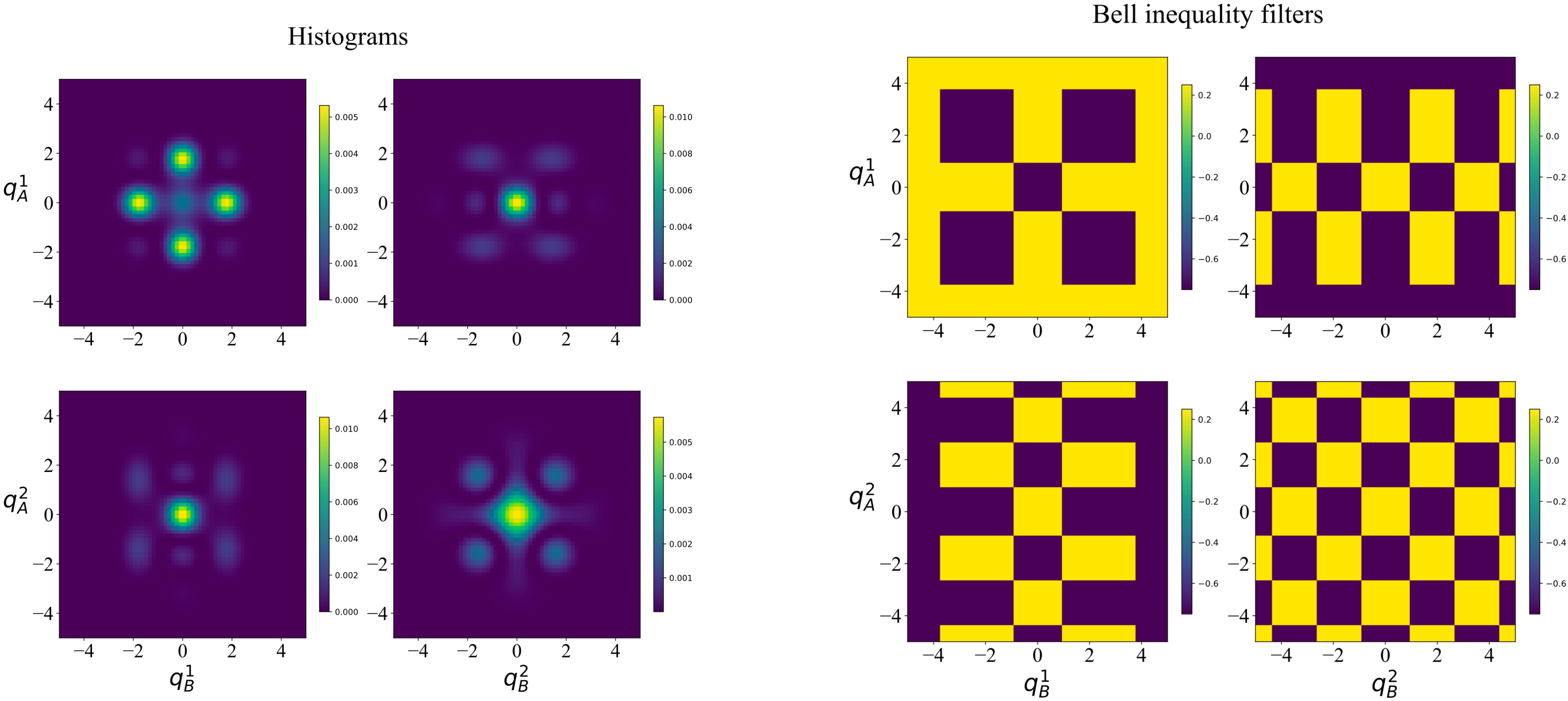


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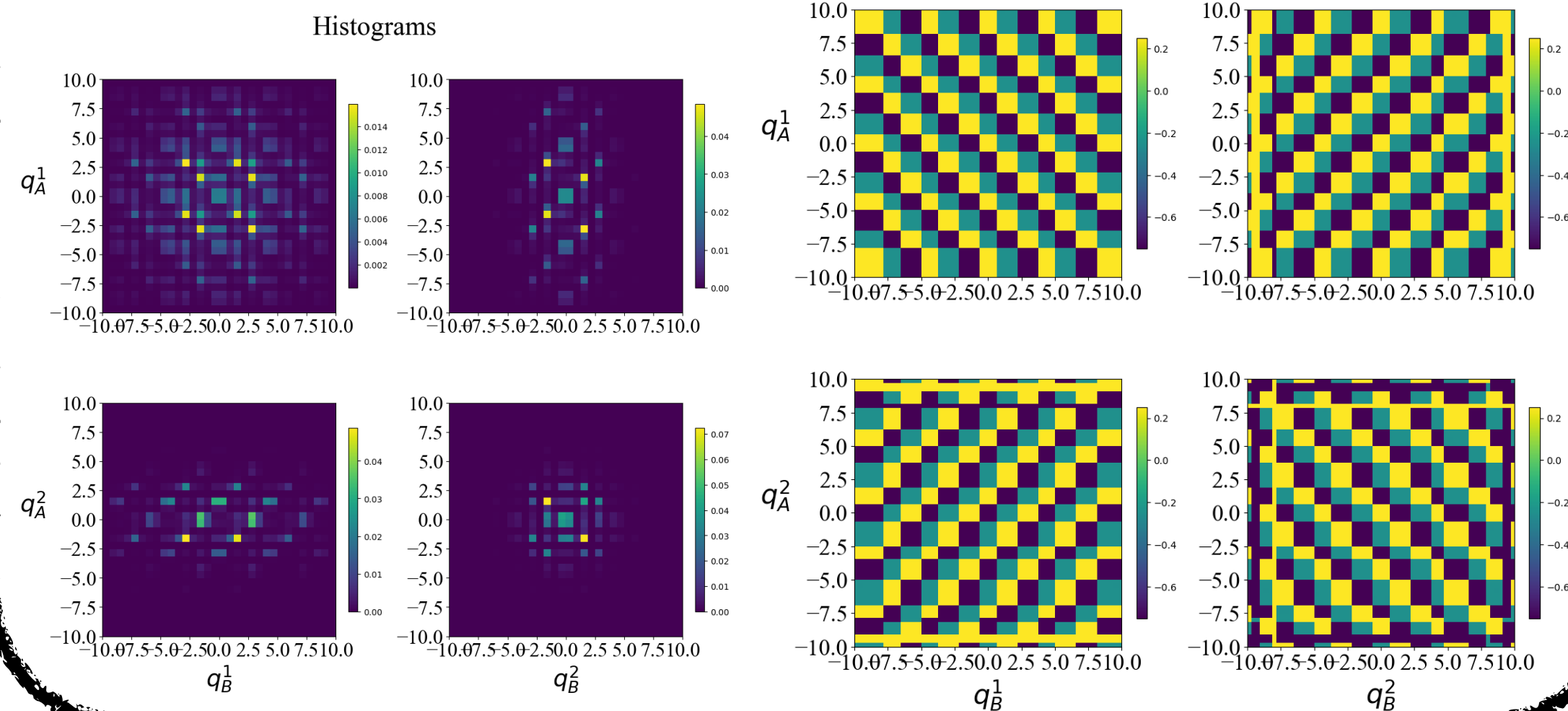
$$CF = 26.2\%$$



Qutrit GKPs

CF: 26 %

Bell inequality filters



Hybrid systems

$$|\psi\rangle = \frac{|0\rangle_{DV}|0\rangle_{CV} + |1\rangle_{DV}|1\rangle_{CV}}{\sqrt{2}}$$

CV encoding: GKP, even vs odd cats ...

Multi-mode systems

$$|\psi\rangle = \frac{|000\rangle_{CV} + |111\rangle_{CV}}{\sqrt{2}}$$

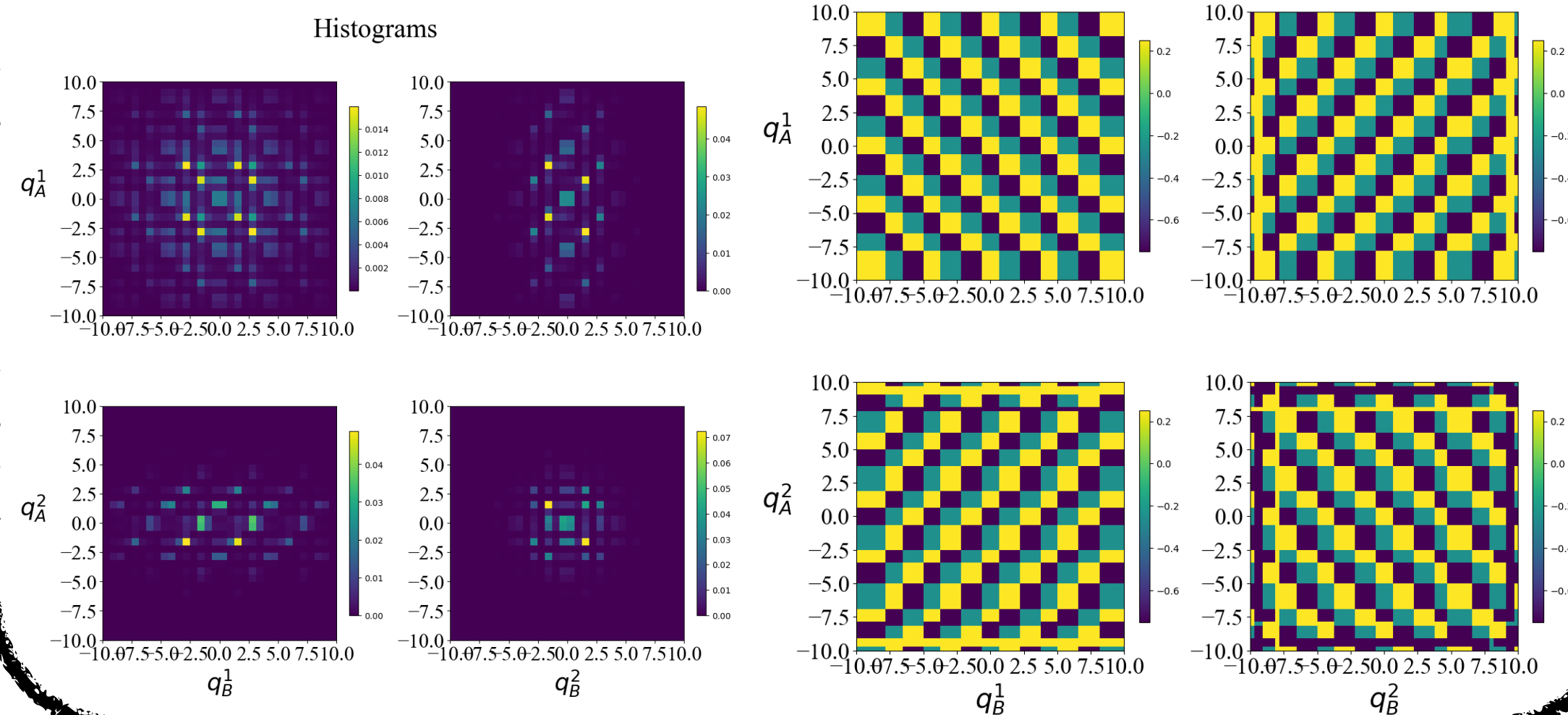
Encoding: GKP (low quality ones)

CF: 46 % !!! (well beyond CHSH)

Qutrit GKPs

CF: 26 %

Bell inequality filters



Hybrid systems

$$|\psi\rangle = \frac{|0\rangle_{DV}|0\rangle_{CV} + |1\rangle_{DV}|1\rangle_{CV}}{\sqrt{2}}$$

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Multi-mode systems

$$|\psi\rangle = \frac{|000\rangle_{CV} + |111\rangle_{CV}}{\sqrt{2}}$$

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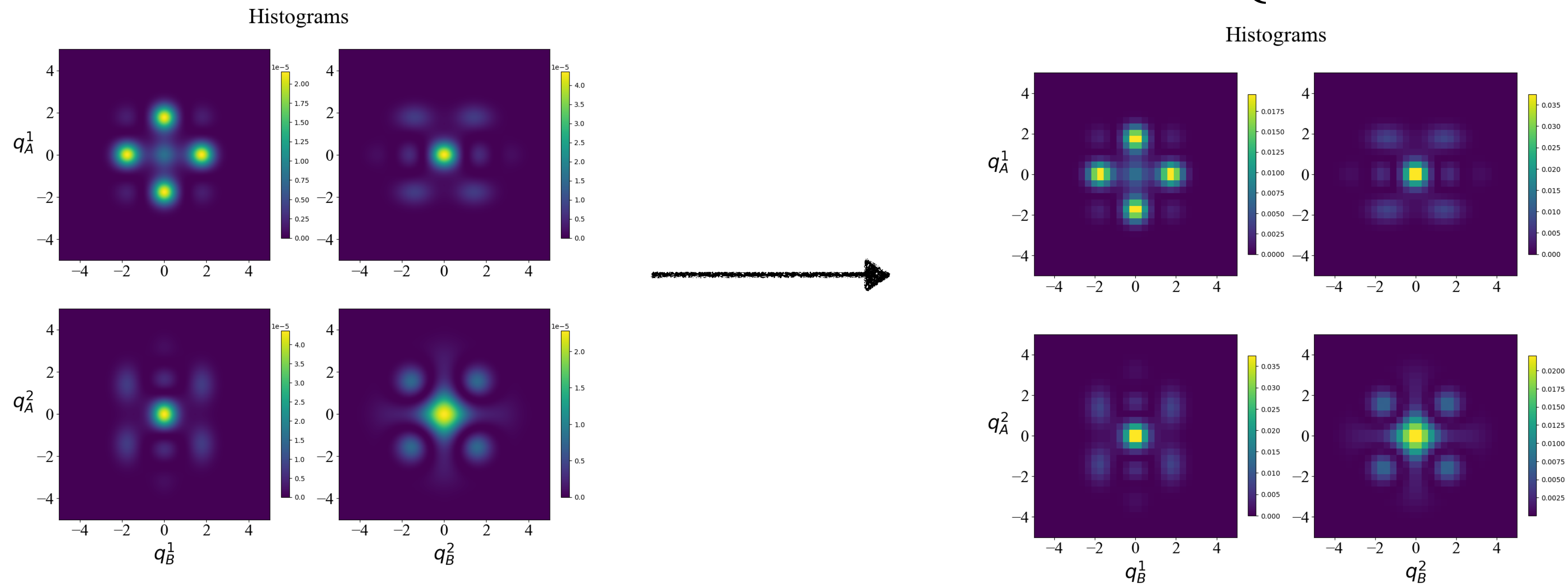
Many open questions:

- moment based inequalities do not exist at low order
- finding good states is a daunting task

Thank you!

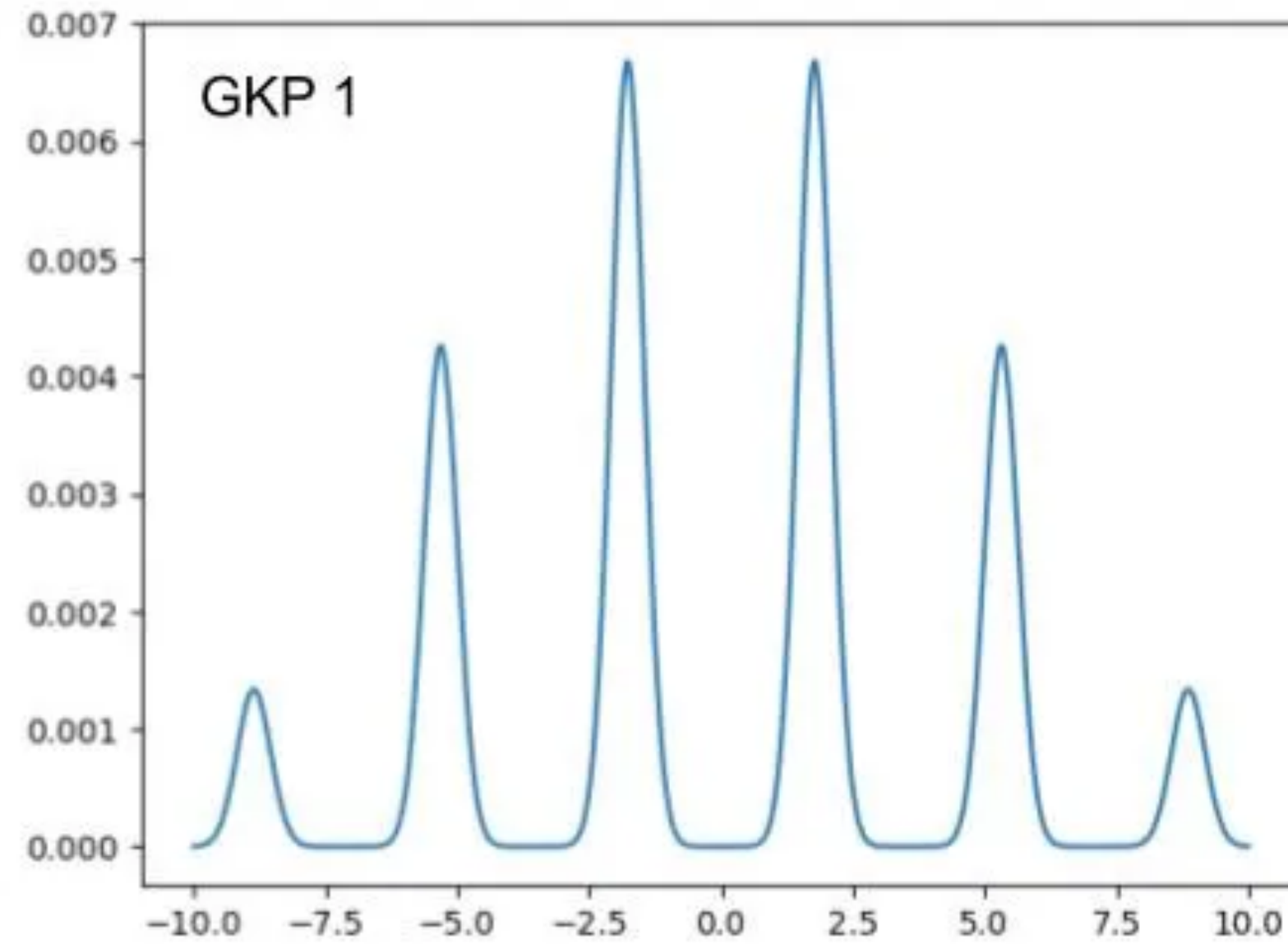
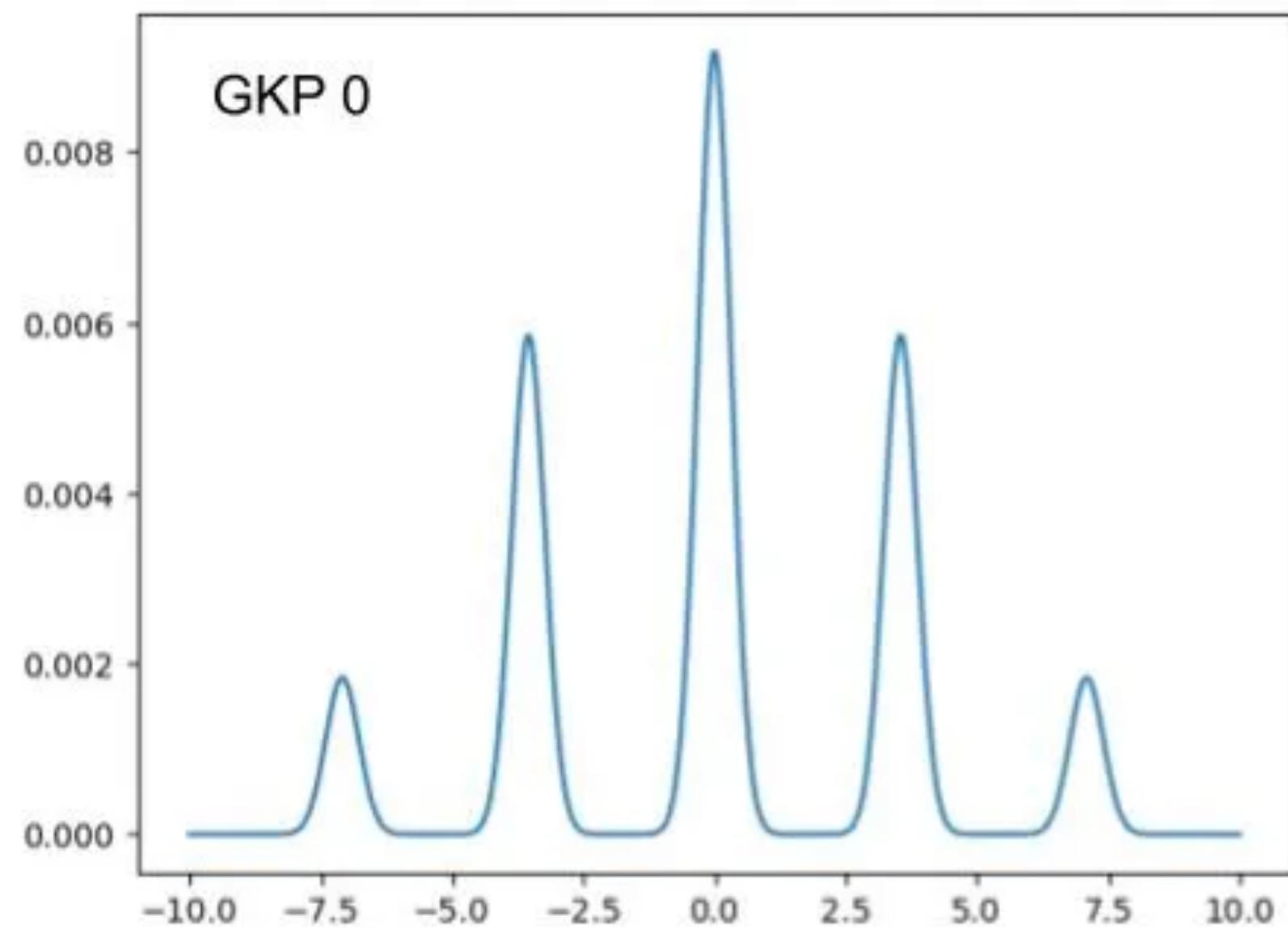
2- Discrete linear program

$$\begin{array}{l}
 \text{Infinite LP (primal)} \\
 (P) \left\{ \begin{array}{l} \text{Find } \mu \in \mathbb{M}_{\pm}((O_X)) \\ \max \quad \mu(O_X) \\ \text{s.t. } \forall C \in \mathcal{M} \mu|_C \leq e_C \\ \mu \geq 0. \end{array} \right.
 \end{array}
 \xrightarrow[N_{bins}]{\text{Discretization}}
 \begin{array}{l}
 (P, D) \left\{ \begin{array}{l} \text{Find } \mu \in \mathbb{M}(N_{bins}^{|X|}) \\ \max \quad \sum_{i,j,k,l} \mu_{ijkl} \\ \text{s.t. } \forall C \in \mathcal{M} \mu|_C \leq e_C \\ \mu \geq 0. \end{array} \right.
 \end{array}$$



GKP entangled state

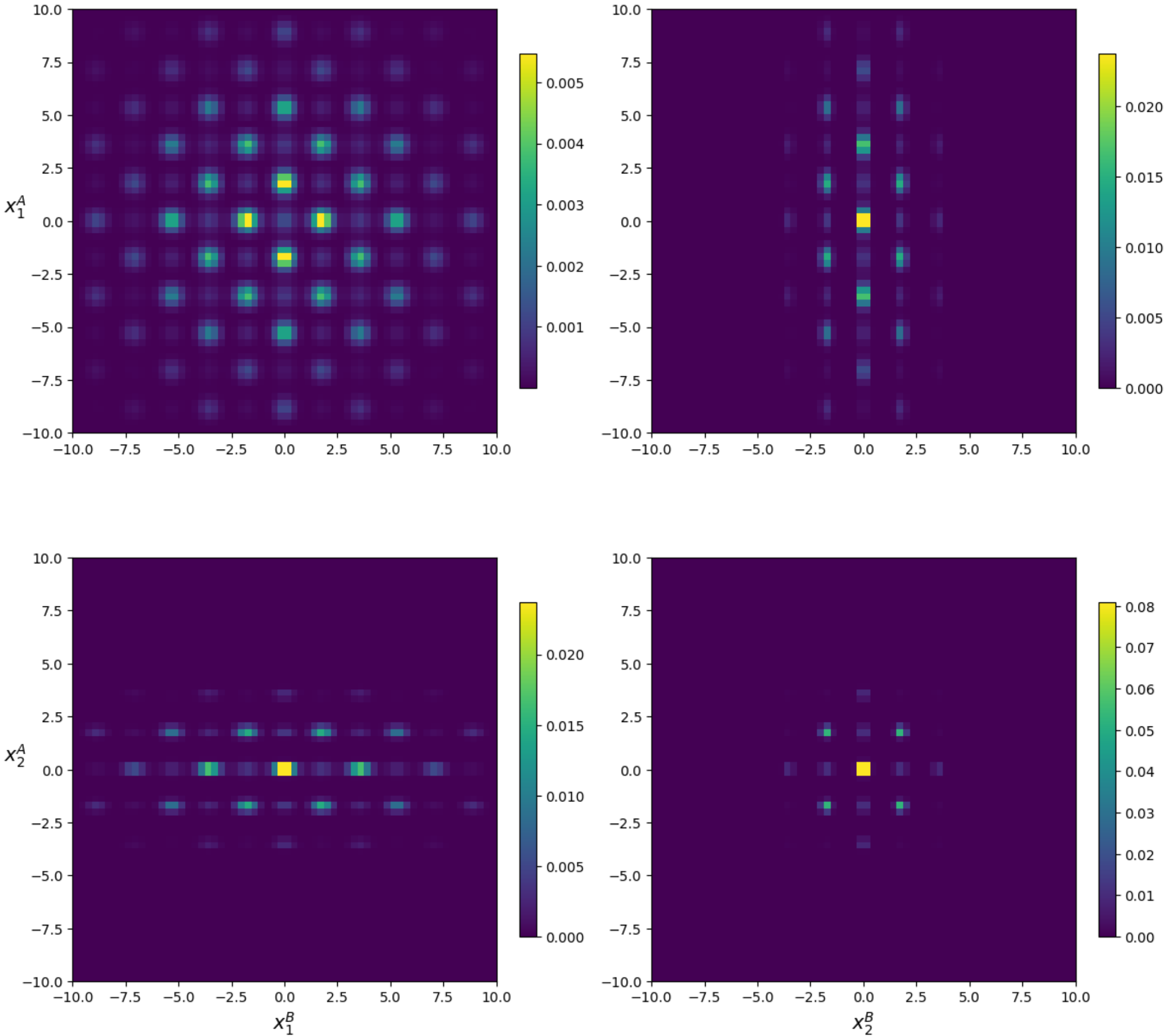
$$|\psi\rangle = \frac{\left(|11\rangle - |00\rangle - (1 + \sqrt{2})(|01\rangle + |10\rangle) \right)}{2\sqrt{2 + \sqrt{2}}}$$



GKP entangled state

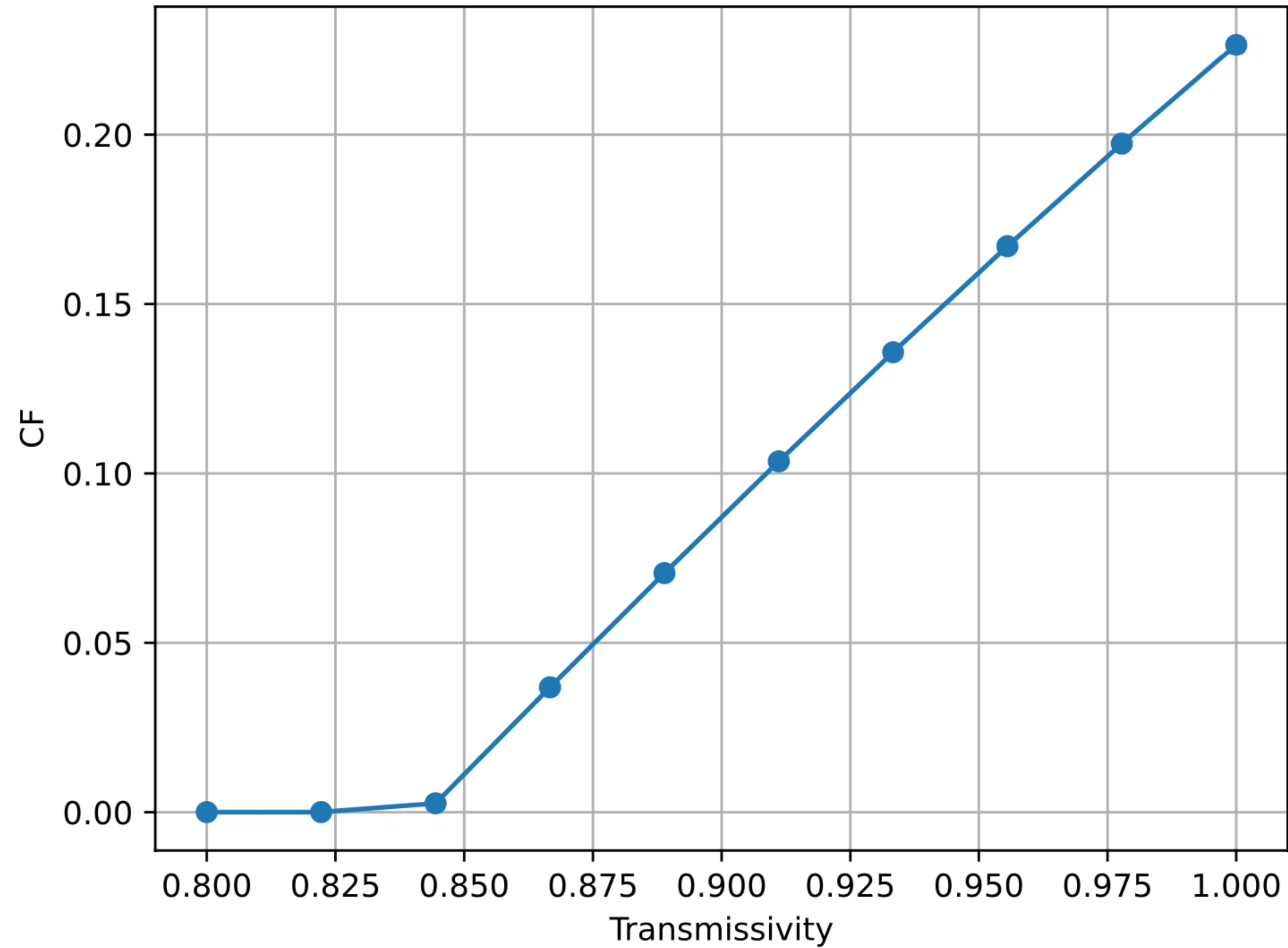
$$|\psi\rangle = \frac{\left(|11\rangle - |00\rangle - (1 + \sqrt{2})(|01\rangle + |10\rangle)\right)}{2\sqrt{2 + \sqrt{2}}}$$

Histograms



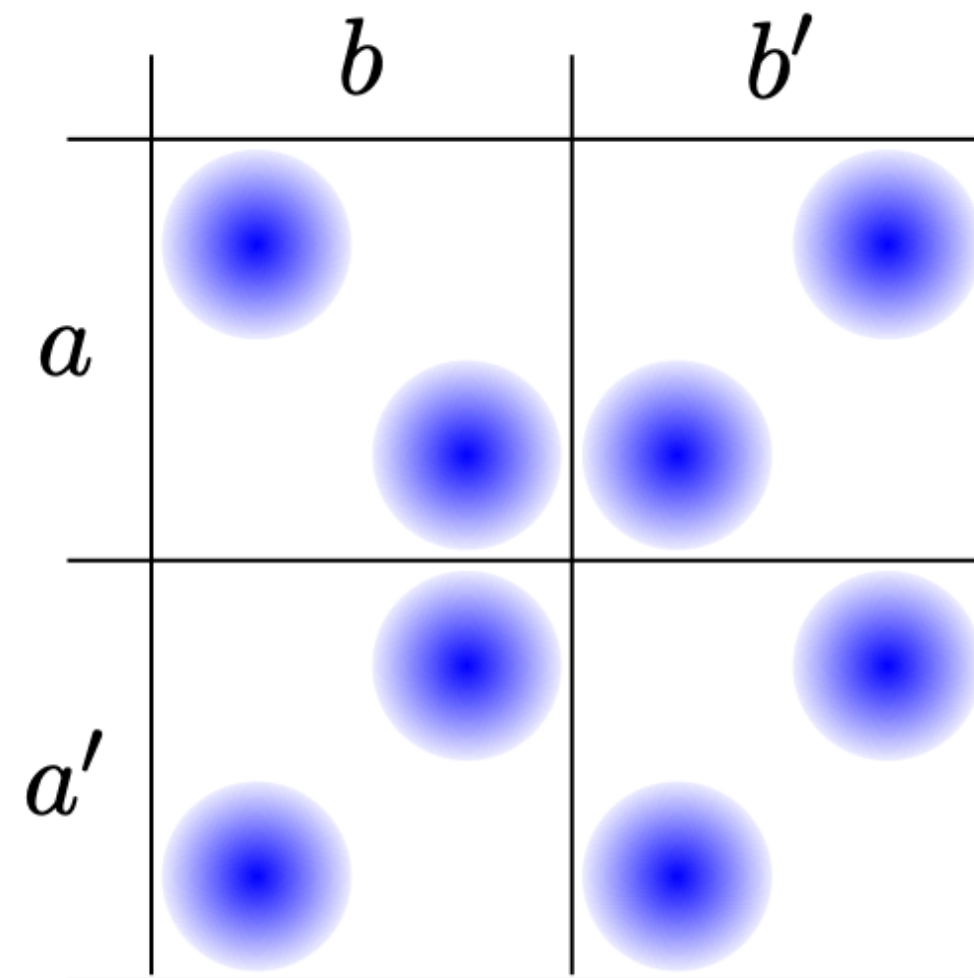
No. bins	8	16	32	64
CF	0	0.2434	0.3452	0.3685

Loss resilience



Generalized Bell inequality

$$\left\{ \begin{array}{l} \text{Find } (\beta_C)_{C \in \mathcal{M}} \in \prod_{C \in \mathcal{M}} C(O_C) \\ \text{maximising } \sum_{C \in \mathcal{M}} \int_{O_C} \beta_C \, d e_C \\ \text{subject to:} \\ \sum_{C \in \mathcal{M}} \beta_C \circ \rho_C^X \leq \mathbf{0}_{O_X} \\ \forall C \in \mathcal{M}, \beta_C \leq |\mathcal{M}|^{-1} \mathbf{1}_{O_C} . \end{array} \right.$$



	0.25 -0.75	-0.75 0.25
	-0.75 0.25	0.25 -0.75
	-0.75 0.25	-0.75 0.25
	0.25 -0.75	0.25 -0.75

if no contextuality

$$e_C \rightarrow \mu_X \quad \sum_{C \in \mathcal{M}} \int_{O_C} \beta_C d e_C = \sum_{C \in \mathcal{M}} \int_{O_X} \beta_C \cdot \rho_C^X d \mu = \int_{O_X} d \mu \left(\sum_C \beta_C \cdot \rho_C^X \right) \leq 0$$